

ECE 342

Electronic Circuits

Lecture 27

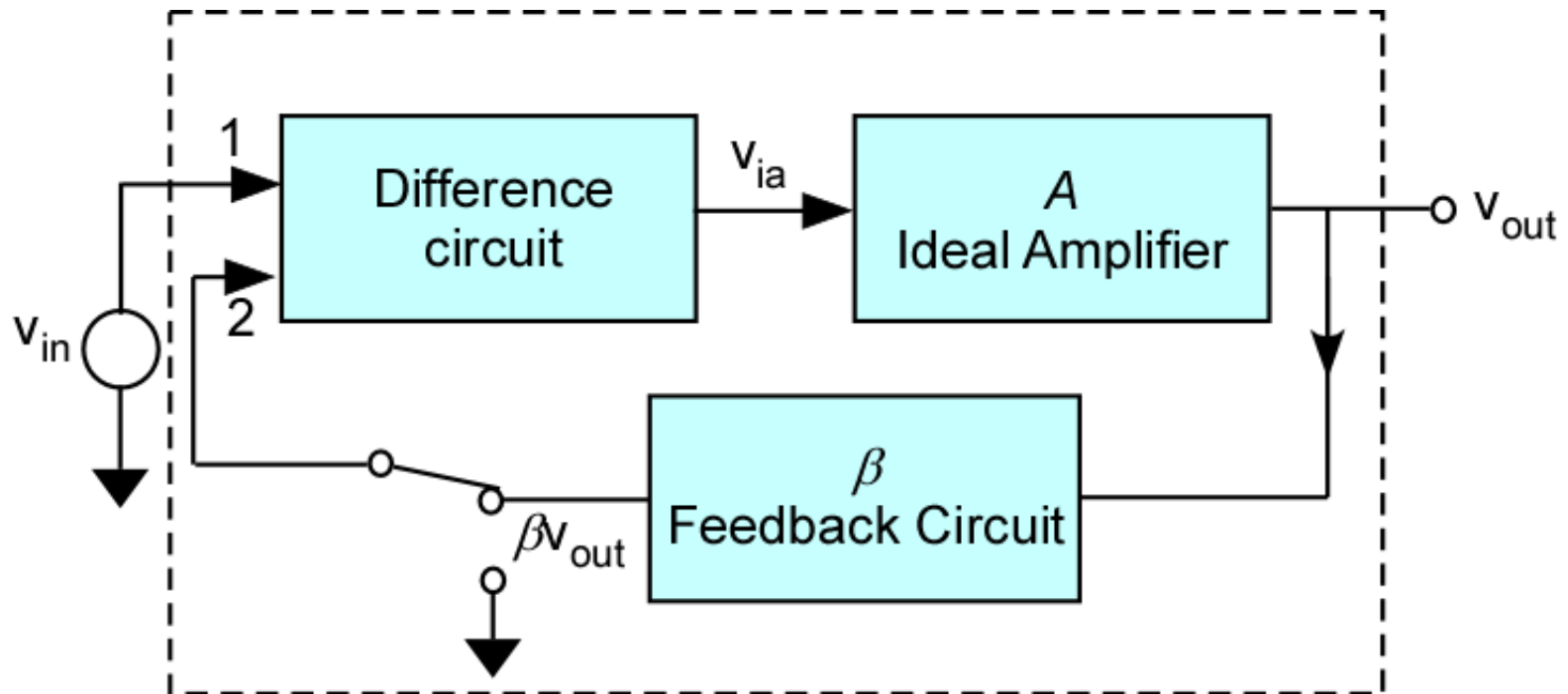
Introduction to Feedback

Jose E. Schutt-Aine
Electrical & Computer Engineering
University of Illinois
jesa@illinois.edu

Feedback

- **Why Use Feedback?**
 1. To desensitize the gain
 2. To reduce nonlinear distortion
 3. To reduce the effect of noise
 4. To control terminal impedances
 5. To increase the bandwidth

Feedback – Basic Concepts



Feedback – Analysis

The ideal amplifier gain is defined by

$$A = \frac{V_{out}}{V_{ia}}$$

The overall gain of the feedback circuit is defined by

$$G = \frac{V_{out}}{V_{in}}$$

If input 2 is grounded

$$V_{ia} = V_{in} - 0 = V_{in}$$

We then get

$$G = \frac{V_{out}}{V_{in}} = \frac{V_{out}}{V_{ia}} = A \quad \text{This is the open-loop gain}$$

Feedback – Analysis

When the switch is closed, then

$$v_{ia} = v_{in} - \beta v_{out}$$

so that

$$v_{out} = A(v_{in} - \beta v_{out}) = Gv_{in}$$

from which we get

$$G = \frac{v_{out}}{v_{in}} = \frac{A}{1 + A\beta} \quad \text{which is the closed-loop gain}$$

The closed-loop gain is always less than the open-loop gain for negative feedback

Feedback – Bandwidth Extension

The high-frequency response of an amplifier (single-pole) is given by:

$$A(s) = \frac{A_M}{1 + s / \omega_H}$$

A_M is the midband gain and ω_H is the upper 3-dB frequency. With negative feedback, we get

$$A_f(s) = \frac{A(s)}{1 + \beta A(s)}$$

After substitution,

$$A_f(s) = \frac{A_M / (1 + A_M \beta)}{1 + s / \omega_H (1 + A_M \beta)}$$

Feedback – Bandwidth Extension

The feedback amplifier will have a midband gain of

$$\frac{A_M}{(1 + A_M \beta)}$$

and an upper 3-dB frequency of $\omega_H (1 + A_M \beta)$

Bandwidth is increased by factor equal to amount of feedback. It can also be shown that the lower 3dB frequency is

$$\frac{\omega_L}{(1 + A_M \beta)}$$

The gain-bandwidth product is constant