ECE 546 Lecture -15 Circuit Synthesis

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MOR via Vector Fitting



Electrical and Computer Engineering University of Illinois at Urbana-Champaig Rational function approximation:

 $f(s) \approx \sum_{n=1}^{N} \frac{c_n}{s-a_n} + d + sh$

Introduce an unknown function σ(s) that satisfies:

$$\begin{bmatrix} \sigma(s)f(s) \\ \sigma(s) \end{bmatrix} \approx \begin{bmatrix} \sum_{n=1}^{N} \frac{c_n}{s - \tilde{a}_n} + d + sh \\ \sum_{n=1}^{N} \frac{\tilde{c}_n}{s - \tilde{a}_n} + 1 \end{bmatrix}$$

• Poles of f(s)= zeros of $\sigma(s)$:



• Flip unstable poles into the left half plane.



Blackbox Formulation

Transfer function is approximated

$$H(\omega) = d + \sum_{k=1}^{L} \frac{c_k}{1 + j\omega / \omega_{ck}}$$

Using curve fitting technique (e.g. vector fitting)

In the time domain, recursive convolution is used

$$y(t) = dx(t-T) + \sum_{k=1}^{L} y_{pk}(t)$$

where

$$y_{pk}(t) = a_k x(t-T) \left(1 - e^{-\omega_{ck}T} \right) + e^{-\omega_{ck}T} y_{pk}(t-T)$$

Recursive convolution is fast



Passivity Enforcement



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- State-space form:
- $\dot{x} = Ax + Bu$ y = Cx + Du
- Hamiltonian matrix:
- $\boldsymbol{M} = \begin{bmatrix} \boldsymbol{A} + \boldsymbol{B}\boldsymbol{K}\boldsymbol{D}^{\mathsf{T}}\boldsymbol{C} & \boldsymbol{B}\boldsymbol{K}\boldsymbol{B}^{\mathsf{T}} \\ -\boldsymbol{C}^{\mathsf{T}}\boldsymbol{L}\boldsymbol{C} & -\boldsymbol{A}^{\mathsf{T}} \boldsymbol{C}^{\mathsf{T}}\boldsymbol{D}\boldsymbol{K}\boldsymbol{B}^{\mathsf{T}} \end{bmatrix}$ $\boldsymbol{K} = \left(\boldsymbol{I} \boldsymbol{D}^{\mathsf{T}}\boldsymbol{D}\right)^{-1} \quad \boldsymbol{L} = \left(\boldsymbol{I} \boldsymbol{D}\boldsymbol{D}^{\mathsf{T}}\right)^{-1}$
- Passive if *M* has no imaginary eigenvalues.
- Sweep: $eig(I S(j\omega)^{H}S(j\omega))$



- Quadratic programming:
 - Minimize (change in response) subject to (passivity compensation).

 $\min(vec(\Delta C)^{\mathsf{T}}\mathsf{H} vec(\Delta C)) \text{ subject to } \Delta \lambda = G \cdot vec(\Delta C).$

Macromodel Circuit Synthesis

Use of Macromodel

- Time-Domain simulation using recursive convolution
- Frequency-domain circuit synthesis for SPICE netlist



Macromodel Circuit Synthesis

Objective: Determine equivalent circuit from macromodel representation

Motivation

• Circuit can be used in SPICE

Goal

• Generate a netlist of circuit elements



Circuit Realization

Circuit realization consists of interfacing the reduced model with a general circuit simulator such as SPICE

Model order reduction gives a transfer function that can be presented in matrix form as

$$S(s) = \begin{bmatrix} s_{11}(s) & \cdot & s_{1N}(s) \\ \cdot & \cdot & \cdot \\ s_{N1}(s) & \cdot & s_{NN}(s) \end{bmatrix}$$

or

$$Y(s) = \begin{bmatrix} y_{11}(s) & \cdot & y_{1N}(s) \\ \cdot & \cdot & \cdot \\ y_{N1}(s) & \cdot & y_{NN}(s) \end{bmatrix}$$



Method 1: Y-Parameter/MOR*

Each of the Y-parameters can be represented as

$$y_{ij}(s) = d + \sum_{k=1}^{L} \frac{a_k}{s - p_k}$$

where the a_k 's are the residues and the p_k 's are the poles. d is a constant

*Giulio Antonini "SPICE Equivalent Circuits of Frequency-Domain Responses", IEEE Transactions on Electromagnetic Compatibility, pp 502-512, Vol. 45, No. 3, August 2003.



Equivalent-Circuit Extraction

Macromodel is curve-fit to take the form

$$Y(s) = d + \sum_{k=1}^{L} \frac{r_k}{s - p_k}$$

Need to find equivalent circuit associated with

- Constant term *d*
- Real Poles
- Complex Poles



Y-Parameter - Circuit Realization

Each of the I_{ij} can be realized with a circuit having the following topology:



The resulting current sources can then be superposed for the total current I_i leaving port *i*

All Y parameters are treated as if they were <u>one-port</u> Y parameters



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Y-Parameter - Circuit Realization

We try to find the circuit associated with each term:

$$y_{ij}(s) = d_{ij} + \sum_{k=1}^{L} \frac{a_{ijk}}{s - p_{ijk}}$$

For a given port *i*, the total current due to all ports with voltages V_i (*j=1,...,P*) is given by

$$I_{i} = \sum_{j=1}^{P} y_{ij} V_{j} = \sum_{j=1}^{P} d_{ij} V_{j} + \sum_{j=1}^{P} V_{j} \sum_{k=1}^{L} \frac{a_{ijk}}{s - p_{ijk}}$$

For each contributing port, with voltage i, the total current due to a voltage V_i at port j is given by

$$I_{ij} = d_{ij}V_{j} + V_{j}\sum_{k=1}^{L} \frac{a_{ijk}}{s - p_{ijk}}$$



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Y-Parameter - Circuit Realization

We try to find the circuit associated with each term:

$$y_{ij}(s) = d + \sum_{k=1}^{L} \frac{a_k}{s - p_k}$$

1. Constant term *d*

$$y_{ijd}(s) = d$$

2. Each pole-residue pair

$$y_{ijk}(s) = \frac{a_k}{s - p_k}$$



Circuit Realization – Constant Term





Circuit Realization – Pole/Residue

In the pole-residue case, we must distinguish two cases

(a) Pole is real
$$y_{ijk}(s) = \frac{a_k}{s - p_k}$$

(b) Complex conjugate pair of poles

$$y_{ijk}(s) = \frac{\alpha_k + j\beta_k}{s - \sigma_k - j\omega_k} + \frac{\alpha_k - j\beta_k}{s - \sigma_k + j\omega_k}$$

In all cases, we must find an equivalent circuit consisting of lumped elements that will exhibit the same behavior



Consider the circuit shown above. The input impedance Z as a function of the complex frequency s can be expressed as:

$$Z = sL + R \qquad Y(s) = \frac{1/L}{s + R/L} \qquad from pole and residue$$

$$\hat{Y}(s) = \frac{1/L}{s + R/L} \qquad \hat{Y}(s) = \frac{a_k}{s - p_k}$$

Comparing Y(s) and $\hat{Y}(s)$ yields the solution

$$L = 1 / a_k \qquad \qquad R = -p_k / a_k$$



Circuit Realization - Complex Poles

Each term associated with a complex pole pair in the expansion gives:

$$\hat{Y} = \frac{r_1}{s - p_1} + \frac{r_2}{s - p_2}$$

Where r_p , r_2 , p_1 and p_2 are the complex residues and poles. They satisfy: $r_1 = r_2^*$ and $p_1 = p_2^*$

It can be re-arranged as:

$$\hat{Y} = (r_1 + r_2) \frac{\left[s - (r_1 p_2 + r_2 p_1) / (r_1 + r_2)\right]}{s^2 - s(p_1 + p_2) + p_1 p_2}$$



Circuit Realization - Complex Poles

The pole/residue representation of the Y parameters is given by:

$$\hat{Y} = (r_1 + r_2) \frac{\left[s - (r_1 p_2 + r_2 p_1) / (r_1 + r_2)\right]}{s^2 - s(p_1 + p_2) + p_1 p_2}$$

DEFINE

 $p = p_1 p_2$ product of poles $a = r_1 + r_2$ sum of residues

 $g = p_1 + p_2$ sum of poles

 $x = r_1 p_2 + r_2 p_1$ cross product

$$\hat{Y} = a \frac{\left[s - x / a\right]}{s^2 - sg + p}$$





Consider the circuit shown above. The input impedance Z as a function of the complex frequency s can be expressed as:

$$Z = sL + R_1 + \frac{1}{1/R_2 + sC} = sL + R_1 + \frac{R_2}{1 + sCR_2}$$

$$Z = \frac{(R_1 + sL)(1 + sCR_2) + R_2}{1 + sCR_2}$$







Circuit Realization - Complex Poles

Comparing

$$Y = \frac{1}{L} \frac{(s+1/CR_2)}{\left[s^2 + s\left(\frac{L+CR_1R_2}{LR_2C}\right) + \frac{(R_1+R_2)}{LR_2C}\right]} \text{ with } \hat{Y} = a\frac{[s-x/a]}{s^2 - sg + p}$$

We can identify the circuit elements

$$L = 1/a$$

$$R_1 = \frac{x}{a^2} - \frac{g}{a}$$

$$R_2 = -\frac{p}{x} - \frac{x}{a^2} + \frac{g}{a}$$

$$C = \frac{pa}{x^2} + \frac{1}{a} - \frac{g}{x}$$



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Circuit Realization - Complex Poles



$$L = 1/a$$

$$R_1 = \frac{x}{a^2} - \frac{g}{a}$$

$$R_2 = -\frac{p}{x} - \frac{x}{a^2} + \frac{g}{a}$$

$$C = \frac{pa}{x^2} + \frac{1}{a} - \frac{g}{x}$$



Negative Elements

In the circuit synthesis process, it is possible that some circuit elements come as negative. To prevent this situation, we add a contribution to the real parts of the residues of the system. In the case of a complex residue, for instance, assume that

$$\hat{Y} = \frac{r_1}{s - p_1} + \frac{r_2}{s - p_2}$$

$$\hat{Y} = \frac{r_1 + \Delta}{\underbrace{s - p_1}} + \frac{r_2 + \Delta}{s - p_2} - \underbrace{\left(\frac{\Delta}{s - p_1} + \frac{\Delta}{s - p_2}\right)}_{Augmented Circuit}$$
Compensation Circuit

Can show that both augmented and compensation circuits will have positive elements



Why S Parameters?



Z_c : microstrip characteristic impedance γ : complex propagation constant *I* : length of microstrip

Y₁₁ can be unstable

S-Parameter Reference Reference Test Line Line Line Test line: Zc, γ Zo Zo $S_{11} = \frac{(1 - e^{-2\gamma l})\Gamma}{1 \Gamma^2 - 2\gamma l}$ $\Gamma = \frac{Z_c - Z_o}{Z_c + Z_o}$ S₁₁ is always stable





Observation: S-parameters decay rapidly; Y parameters do not.







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Method 2: S-Parameter /MOR





$$A_{i}(\omega) = \frac{l}{2} \left[V_{i}(\omega) + Z_{o}I_{i}(\omega) \right]$$

$$B_{i}(\omega) = \frac{1}{2} \left[V_{i}(\omega) - Z_{o}I_{i}(\omega) \right]$$

Need equivalent circuit for S_{ijk}

All S parameters are treated as if they were <u>one-port</u> S parameters

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Strategy

For a given circuit, a relationship between the input admittance $Y_{ijk}(s)$ of the circuit and the associated one-port S-parameter representation $S_{ijk}(s)$ can be described by

$$S_{ijk}(s) = \frac{Y_o - Y_{ijk}(s)}{Y_o + Y_{ijk}(s)} \qquad Y_{ijk}(s) = Y_o \frac{1 - S_{ijk}(s)}{1 + S_{ijk}(s)}$$

Y_o is the reference admittance



Equivalent-Circuit Extraction

Macromodel is curve-fit to take the form

$$S(s) = d + \sum_{k=1}^{L} \frac{r_k}{s - p_k}$$

Need to find equivalent circuit associated with

- Constant term *d*
- Real Poles
- Complex Poles



Constant Term

$$R = \left(\frac{1 - S_{ijk}}{1 + S_{ijk}}\right) Y_o = \left(\frac{1 - d}{1 + d}\right) Y_o$$





S- Circuit Realization – Constant Term





S-Parameters - Poles and Residues

In the pole-residue case, we must distinguish two cases

(a) Pole is real
$$S_{ijk}(s) = \frac{a_k}{s - p_k}$$

(b) Complex conjugate pair of poles

$$s_{ijk}(s) = \frac{\alpha_k + j\beta_k}{s - \sigma_k - j\omega_k} + \frac{\alpha_k - j\beta_k}{s - \sigma_k + j\omega_k}$$

In all cases, we must find an equivalent circuit consisting of lumped elements that will exhibit the same behavior



S-Realization – Real Poles



Admittance of proposed model is given by:







from pole and residue



Solution for Real Poles





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From the S-parameter expansion, the complex pole pair gives:

$$\hat{S} = \frac{r_1}{s - p_1} - \frac{r_2}{s - p_2} = \frac{s(r_1 + r_2) - (r_1 p_2 + r_2 p_1)}{s^2 - s(p_1 + p_2) + p_1 p_2}$$

which corresponds to an admittance of:

$$\hat{Y} = Y_o \left(\frac{1-\hat{S}}{1+\hat{S}}\right) = \left(\frac{1-\frac{sa-x}{s^2-sg+p}}{1+\frac{sa-x}{s^2-sg+p}}\right)Y_o$$



The admittance expression can be re-arranged as

$$\hat{Y} = \left(\frac{s^2 - sg + p - sa + x}{s^2 - sg + p + sa - x}\right) Y_o = \left(\frac{s^2 - s(g + a) + p + x}{s^2 - s(g - a) + p - x}\right) Y_o$$

WE HAD DEFINED

 $p = p_1 p_2$ product of poles $a = r_1 + r_2$ sum of residues

 $g = p_1 + p_2$ sum of poles

 $x = r_1 p_2 + r_2 p_1$ cross product



$$\hat{Y} = \left(\frac{s^2 - sg + p - sa + x}{s^2 - sg + p + sa - x}\right) Y_o = \left(\frac{s^2 - s(g + a) + p + x}{s^2 - s(g - a) + p - x}\right) Y_o$$

This can be further rearranged as

$$\hat{Y} = \left(\frac{s^2 + sA + B}{s^2 + sD + F}\right)E$$

in which

$$A = -(g+a), \ B = p+x, \ D = -(g-a), \ F = p-x$$

and $E = Y_o = \frac{1}{H}$



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There are several circuit topologies that will work





More circuit topologies that will work

Model 10











Model 12



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Complex Poles – Model 1

In particular, if we choose model 1



Must be matched with

$$\hat{Y} = Y_o \left(\frac{1 - S_{ijk}}{1 + S_{ijk}} \right) = \left(\frac{1 - \frac{sa - x}{s^2 - sg + p}}{1 + \frac{sa - x}{s^2 - sg + p}} \right) Y_o$$



Complex Poles – Model 1

Matching the terms with like coefficients gives

$$R_o = \frac{1}{Y_o}$$

-

$$p + x = \frac{R_o + R_1 + R_2}{LCR_2}$$

$$p - x = \frac{R_1 + R_2}{LCR_2}$$

$$2p = \frac{R_o + 2R_1 + 2R_2}{LCR_2}$$

$$2x = \frac{R_o}{LCR_2}$$





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Complex Poles – Model 9

If we choose Model 9





from which the circuit elements can be extracted



Complex Poles – Model 9





$$R_{2} = \frac{\left(-BD^{2} + BF + ADF - F^{2}\right)}{\left(B^{2} - ABD + BD^{2} + A^{2}F - 2BF - ADF + F^{2}\right)H}$$

$$R_{3} = \frac{F}{(-B+F)H} \qquad \qquad L = \frac{-B D + A F}{(B^{2} - ABD + BD^{2} + A^{2}F - 2BF - ADF + F^{2})H}$$

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Special Case – Model 4

A special case exists when x=0or $x = r_1p_2 + r_2p_1 = 0$

$$\hat{Y} = \left(\frac{s^2 - s(g+a) + p + x}{s^2 - s(g-a) + p - x}\right) Y_o = \left(\frac{s^2 - s(g+a) + p}{s^2 - s(g-a) + p}\right) Y_o$$

$$\hat{Y} = \left(\frac{s^2 + sA + B}{s^2 + sD + B}\right)E$$

in which

$$A = -(g + a), B = p + x, D = -(g - a), F = p$$

and $E = Y_o = \frac{1}{H}$



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Special Case – Model 4

The proposed circuit model is



This model has one inductor, one capacitor and two resistors.







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Method 3 - Convolution with S Parameters



In frequency domain *B=SA*

In time domain b(t) = s(t) * a(t)Convolution: $s(t) * a(t) = \int_{-\infty}^{\infty} s(t - \tau) a(\tau) d\tau$



SPICE Macromodel



Most of the computational effort is in the convolution calculation of the history H(t) at each time step.

$$H(t) = \sum_{\tau=1}^{t-1} s(\tau) a(t-\tau) \Delta \tau \quad \longleftarrow \begin{array}{l} \text{This operation can} \\ \text{be accelerated} \end{array}$$

We make the convolution faster using a δ -function expansion for s(t)



S-Parameter Expansion

In the frequency domain, assume that S parameter can be expanded in the form:

$$S(l) = \sum_{k=1}^{M} c_k e^{j2\pi lk}$$

In the time domain, this corresponds to:

$$s(p) = \sum_{k=1}^{M} c_k \delta(p-k)$$

Which is an impulse train of order *M*. Convolution will then give:

$$y(p) = s(p) * x(p) = \left[\sum_{k=1}^{M} c_k \delta(p-k)\right] * x(p) = \sum_{k=1}^{M} c_k x(p-k)$$

If we truncate the summation to the Q largest impulses:

$$y(p) = \left[\sum_{k=1}^{Q} c_k \delta(p-k)\right] * x(p) = \sum_{k=1}^{Q} c_k x(p-k)$$

If the reference system is optimized, most of the coefficients c_k will be negligibly small; therefore $\Rightarrow Q$ will be a relatively small number

Fast Convolution is achieved by making Q small



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Strategy

$$s_{ijk}(u) = c_{ijk}\delta(u-k)$$

Since the S-parameter is a simple delay, the oneport circuit representation is a transmission line with characteristic impedance Z_o and delay k



Circuit Interpretation

 $s_{ijk}(u) = c_{ijk}\delta(u-k)$





Method 1: Y-Parameters/MOR



Recursive convolution



SPICE realization



Method 2: S-Parameters/MOR



Recursive convolution

SPICE realization



Comparisons

SPICE simulation from MOR generated Netlist (Method 2)







Coupled Lines (4-port)

Direct









Comparison of S-methods



