

ECE 546

Lecture -19

X-Parameters

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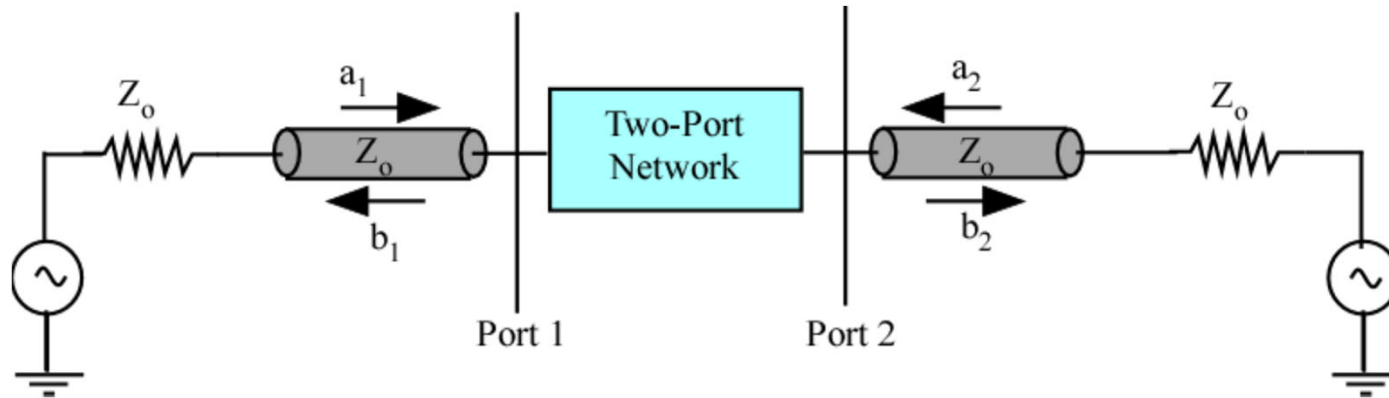
References

[1] J J. Verspecht and D. E. Root, "Polyharmonic Distortion Modeling," IEEE Magazine, June 2006, pp. 44-57.

[2] D.E. Root, J. Verspecht, D. Sharrit, J. Wood, and A. Cognata, "Broad-band poly-harmonic distortion (PHD) behavioral models from fast automated simulations and large-signal vectorial network measurements," IEEE Trans. Microwave Theory Tech., vol. 53, no. 11, pp. 3656–3664, Nov. 2005.

[3] D.E. Root, J. Verspecht, J. Horn, J. Wood, and M. Marcu, "X Parameters", Cambridge University Press, 2013.

Scattering Parameters



For a two-port

$$V_1 = a_1 + b_1$$

$$I_1 = \frac{a_1 - b_1}{Z_0}$$

$$b_1 = S_{11}a_1 + S_{12}a_2$$

$$b_2 = S_{21}a_1 + S_{22}a_2$$

$$V_2 = a_2 + b_2$$

$$I_2 = \frac{a_2 - b_2}{Z_0}$$

For a general N-port

$$B = SA$$

$$B_i = \sum_{j=1}^N S_{ij} A_j$$

$$S_{ij} = \left. \frac{B_i}{A_j} \right|_{\substack{A_k=0 \\ k \neq j \\ k=1, \dots, N}}$$

“...most successful behavioral models...”

X Parameters: Motivation

S Parameters are a very powerful tool for signal integrity analysis.

Today, X parameters are primarily used to characterize power amplifiers and nonlinear devices.
Not yet applied to signal integrity.

X Parameters

Purpose

Characterize nonlinear behavior of devices and systems

Advantages

- Mathematically robust framework
- Can handle nonlinearities
- Instrument exists (NVNA)
- Blackbox format → vendor IP protection
- Matrix format → easy incorporation in CAD tools
- X Parameters are a *superset* of S parameters

Challenges in HS Links

High speed Serial channels are pushing the current limits of simulation. Models/Simulator need to handle current challenges

- Need to accurately handle very high data rates
- Simulate large number of bits to achieve low BER
- Non-linear blocks with time variant systems
- Model TX/RX equalization
- All types of jitter: (random, deterministic, etc.)
- Crosstalk, loss, dispersion, attenuation, etc...
- Handle and manage vendor specific device settings
- Clock data recovery (CDR) circuits

These cannot be accurately modeled with S parameters

Motivation

Limitation: S Parameters only work for linear systems. Many networks and systems are nonlinear

- **Applications**

- High-speed links, power amplifiers, mixed-signal circuits

- **Existing Methods**

- Load pull techniques

- IBIS models

- Models are flawed and incomplete

PHD Modeling

- Polyharmonic distortion (PHD) modeling is a frequency-domain modeling technique
- PHD model defines X parameters which form a superset of S parameters
- To construct PHD model, DUT is stimulated by a set of harmonically related discrete tones
- In stimulus, fundamental tone is dominant and higher-order harmonics are smaller

PHD Framework

- **Signal is represented by a fundamental with harmonics**
- **Signals are periodic or narrowband modulated versions of a fundamental with harmonics**
- **Harmonic index: 0 for dc contribution, 1 for fundamental and 2 for second harmonic**
- **Power level, fundamental frequency can be varied to generate complete data for DUT**

PHD Framework

- **Stimulus**
 - A-waves are incident and B-waves are scattered
- **Reference System Z_C**
 - Default value is 50 ohm

For a given port with voltage V and current I

$$A = \frac{V + Z_C I}{2}$$

$$B = \frac{V - Z_C I}{2}$$

PHD Framework

F_{pm} describes a time-invariant system \rightarrow delay in time domain corresponds to phase shift in frequency domain

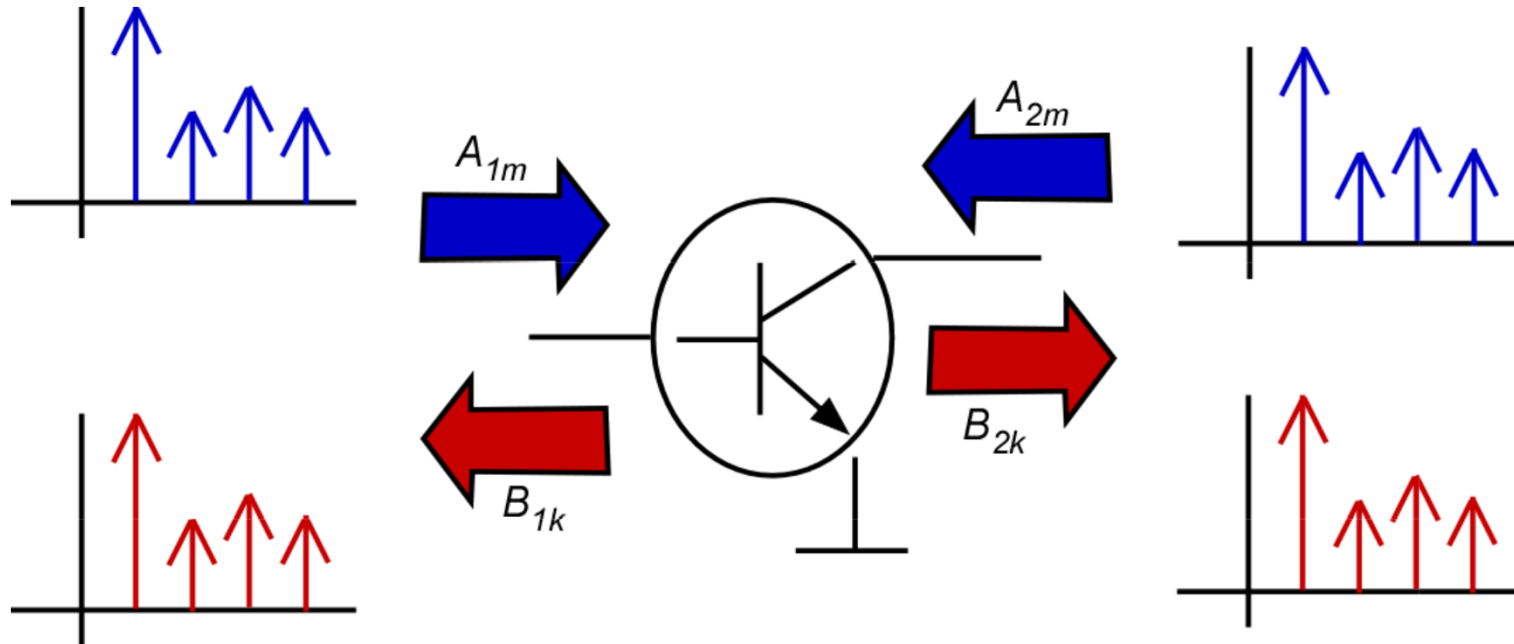
$$B_{pm} e^{jm\theta} = F_{pm} \left(A_{11} e^{j\theta}, A_{12} e^{j2\theta}, \dots, A_{21} e^{j\theta}, A_{22} e^{j2\theta}, \dots \right)$$

For phase normalization, define

$$P = e^{+j\phi(A_{11})}$$

$$B_{pm} = F_{pm} \left(|A_{11}|, A_{12} P^{-2}, A_{13} P^{-3}, \dots, A_{21} P^{-1}, A_{22} P^{-2}, \dots \right) P^{+m}$$

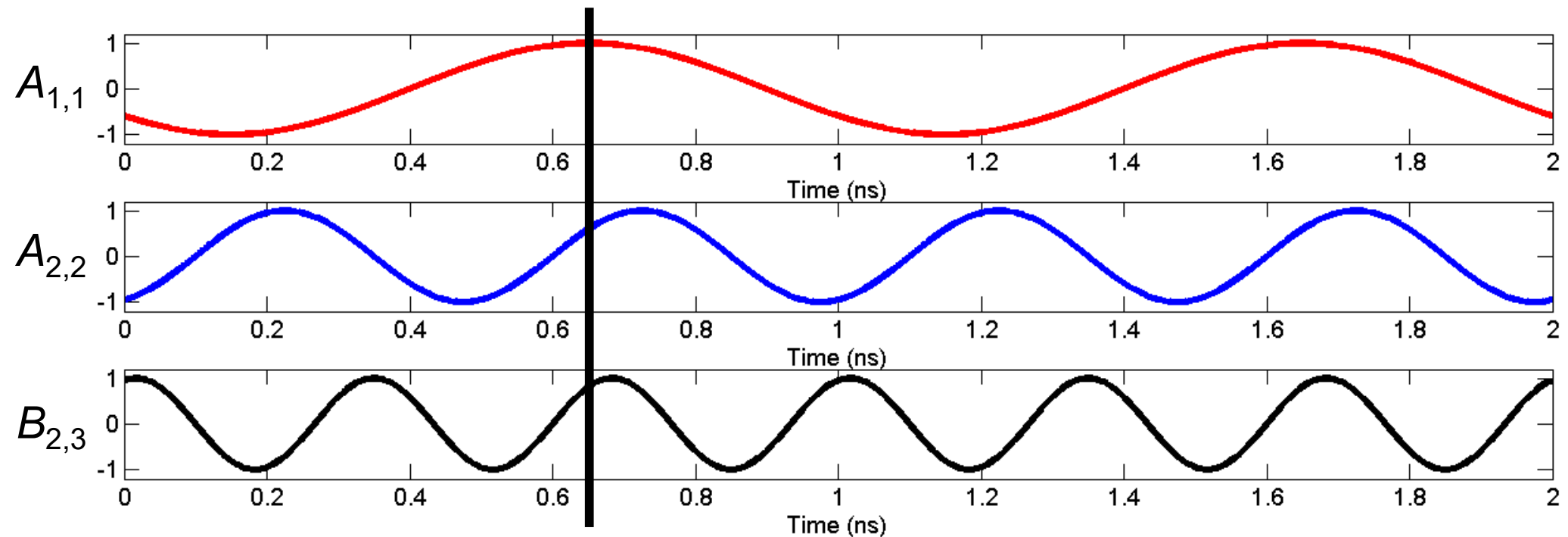
PHD Framework



$$B_{1k} = F_{1k}(A_{11}, A_{12}, \dots, A_{21}, A_{22}, \dots)$$
$$B_{2k} = F_{2k}(A_{11}, A_{12}, \dots, A_{21}, A_{22}, \dots)$$

Cross-Frequency Phase for Commensurate Tones

- Defined as the phase of each pseudowave when the fundamental, $A_{1,1}$, has zero phase.
- $B_{2,3}$ can be related to $A_{2,2}$ in magnitude and phase.

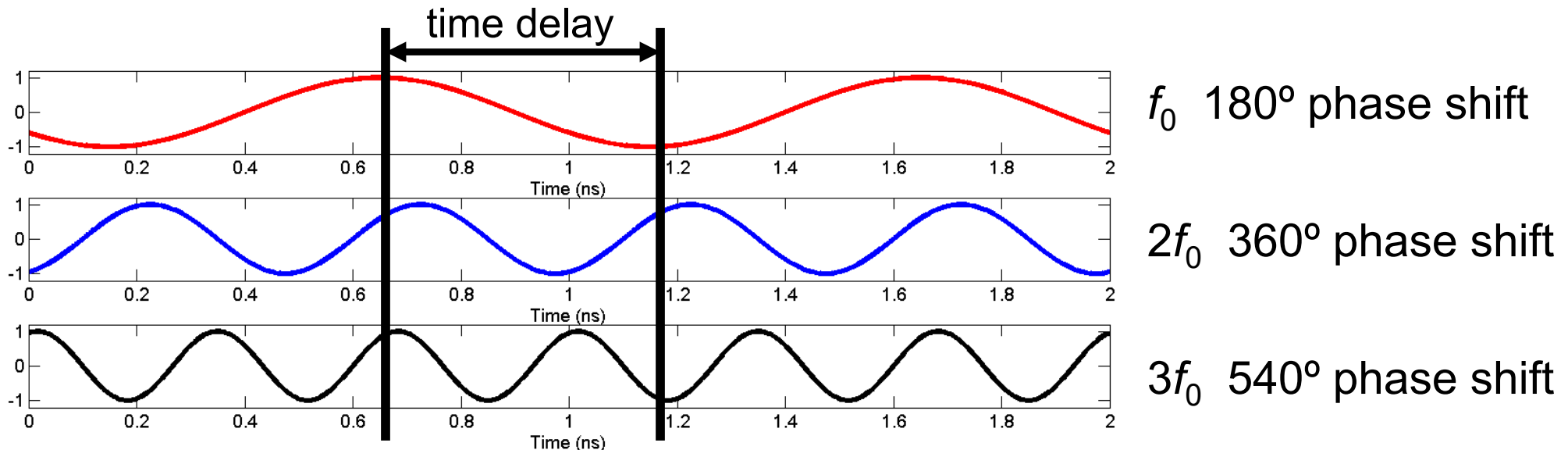


Time-Invariance Property of Nonlinear Scattering Function

$$F_{p,k}(A_{1,1}e^{j\theta}, A_{1,2}(e^{j\theta})^2, A_{1,3}(e^{j\theta})^3, \dots)$$

$$= F_{p,k}(A_{1,1}, A_{1,2}, A_{1,3}, \dots)(e^{j\theta})^k$$

- Shifting all of the inputs by the same time means that different harmonic components are shifted by different phases.



Defining Phase Reference

- Can use time-invariance to separate magnitude and phase dependence of one incident pseudowave.

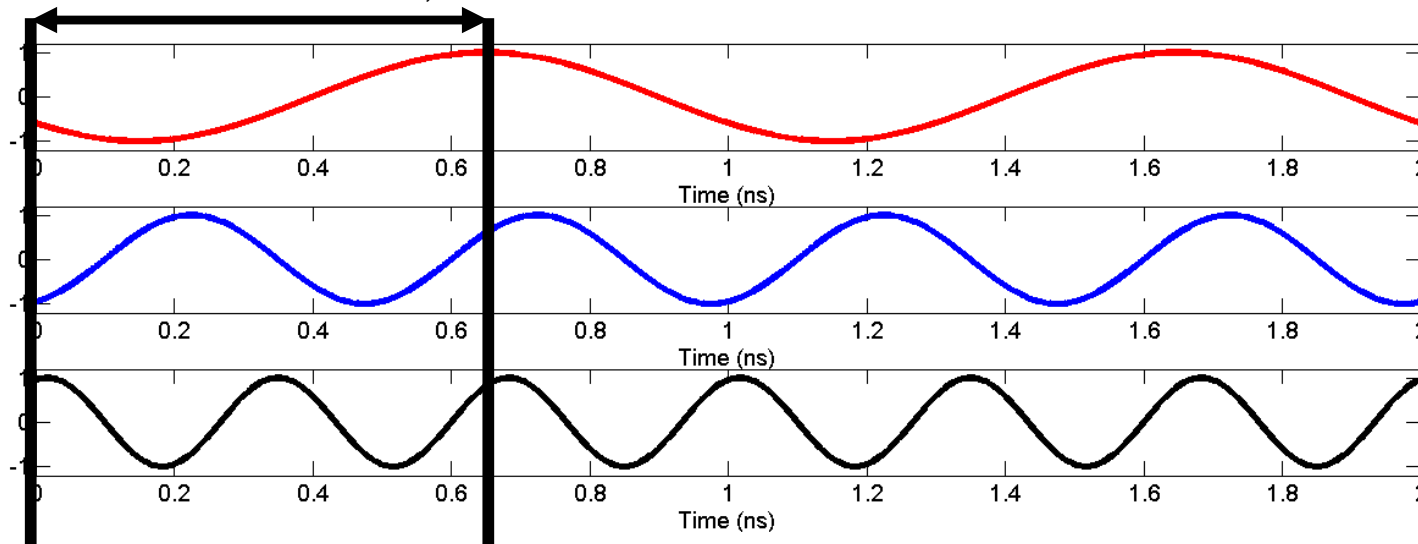
$$B_{p,k} = F_{p,k}(A_{1,1}, A_{1,2}, A_{1,3}, \dots)$$

using

$$= F_{p,k}(|A_{1,1}|, A_{1,2}P^{-2}, A_{1,3}P^{-3}, \dots)P^k$$

$$P = \frac{A_{1,1}}{|A_{1,1}|} = e^{j\arg(A_{1,1})}$$

Shifting reference to zero phase of $A_{1,1}$.



Commensurate Tones

X-Parameter Formalism*

- Define $X_{p,k}^{(FB)}(|A_{1,1}|, A_{1,2}P^{-2}, A_{1,3}P^{-3}, \dots)$
 $= F_{p,k}(A_{1,1}, A_{1,2}, A_{1,3}, \dots)P^{-k}$



$$B_{p,k} = X_{p,k}^{(FB)}(|A_{1,1}|, A_{1,2}P^{-2}, A_{1,3}P^{-3}, \dots)P^k$$

- Still difficult to characterize this nonlinear term.
- If only one incident pseudowave, $A_{1,1}$, is large then the other smaller inputs can be linearized about the large-signal response of $F_{p,k}$ to only $A_{1,1}$.

*D. E. Root, *et al.*, *X-Parameters*, 2013.

PHD Framework

Define variables

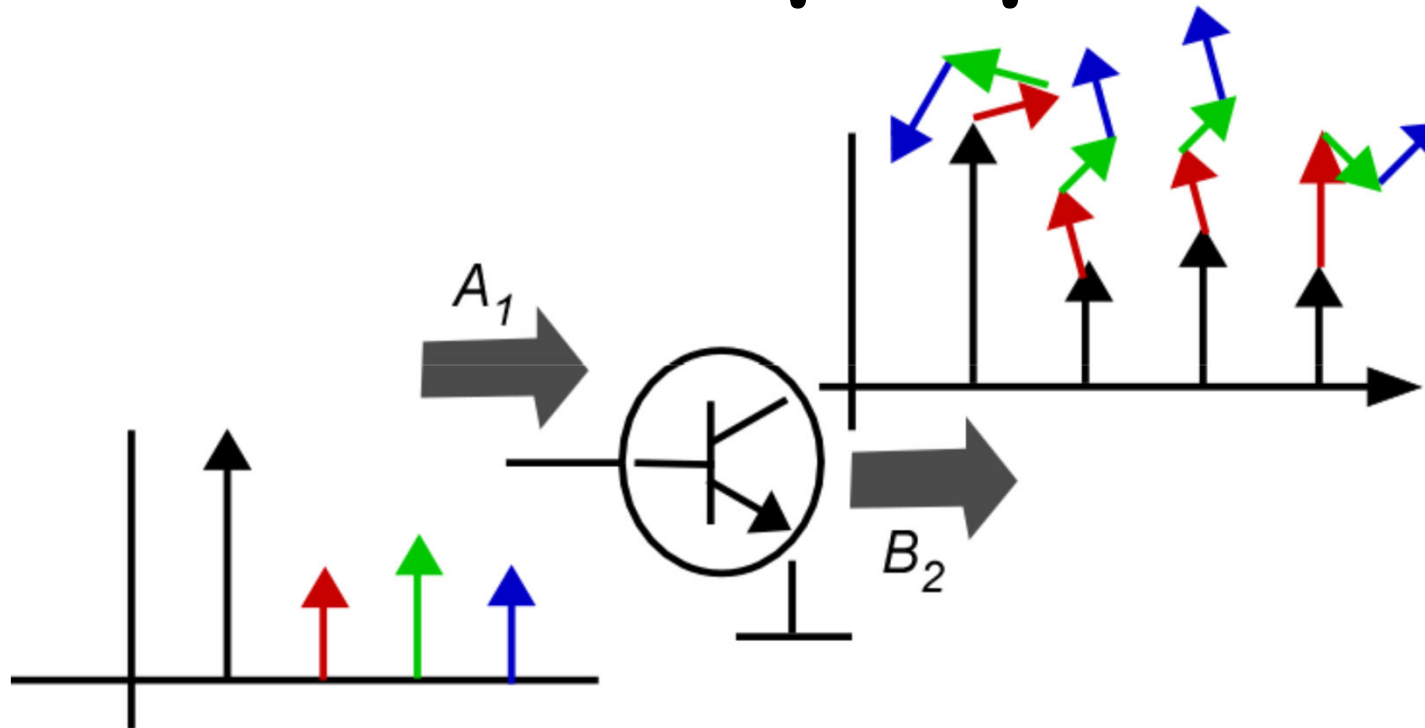
A_{pm}
port harmonic

B_{pm}
port harmonic

- Introduce multivariate complex function F_{pm} such that

$$B_{pm} = F_{pm} (A_{11}, A_{12}, \dots, A_{21}, A_{22}, \dots)$$

Harmonic Superposition



In many situations, there is only one dominant large-signal input component present. The harmonic frequency components are relatively small \rightarrow harmonic components can be superposed

Harmonic superposition principle is key to PHD model

Nonanalytical Mapping*

A nonlinearity described by:

$$f(x) = \alpha x + \gamma x^3$$

Signal is sum of main signal and additional **perturbation term which is assumed to be small**

$$x(t) = x_o(t) + \Delta x(t)$$

* see: J. Verspecht and D. E. Root, "Polyharmonic Distortion Modeling," IEEE Magazine, June 2006, pp. 44-57.

Case 1

Consider the signal $x(t)$, given by the sum of a real dc component and a small tone at frequency f

$$x_o(t) = A$$

A is real

$$\Delta x(t) = \frac{\delta e^{j\omega t} + \delta^* e^{-j\omega t}}{2}$$

δ is a small complex number

The linear response in $\Delta x(t)$ can be computed by

$$\Delta(y(t)) = f(x_o(t) + \Delta x(t)) - f(x_o(t))$$

Case 1

$$\Delta(y(t)) \approx f'(x_o(t))\Delta x(t)$$

For case 1, we evaluate the conductance nonlinearity $f'(x_o)$ at the fixed value $x_o=A$

$$f'(A) = \alpha + 3\gamma A^2$$

After substitution, we get

$$\Delta(y(t)) = \left[\alpha + 3\gamma A^2 \right] \left(\frac{\delta e^{j\omega t} + \delta^* e^{-j\omega t}}{2} \right)$$

The complex coefficient of term proportional to $e^{j\omega t}$ is

$$\left[\frac{\alpha + 3\gamma A^2}{2} \right] \delta \quad \rightarrow \text{Linear input-output relationship}$$

Case 2

Now, $x_o(t)$ is a periodically time-varying signal:

$$x_o(t) = A \cos(\omega t)$$

$$\Delta x(t) = \frac{\delta e^{j\omega t} + \delta^* e^{-j\omega t}}{2}$$

Evaluating the conductance nonlinearity at $x_o(t)$ gives

$$\begin{aligned} f'(A \cos(\omega t)) &= \alpha + 3\gamma A^2 \cos(\omega t) \\ &= \left(\alpha + \frac{3\gamma A^2}{2} \right) + \frac{3\gamma A^2}{2} \cos(2\omega t) \end{aligned}$$

Case 2

We can evaluate $\Delta(y(t))$ to get:

$$\Delta(y(t)) = \left[\left(\alpha + \frac{3\gamma A^2}{2} \right) + \frac{3\gamma A^2}{2} \left(\frac{e^{2j\omega t} + e^{-2j\omega t}}{2} \right) \right] \\ \times \left(\frac{\delta e^{j\omega t} + \delta^* e^{-j\omega t}}{2} \right)$$

Now, we have terms proportional to $e^{j\omega t}$ and $e^{j3\omega t}$ and their complex conjugates. Restrict attention to complex term proportional to $e^{j\omega t}$

Case 2

The complex coefficient of term proportional to $e^{j\omega t}$ is

$$\left(\frac{\alpha}{2} + \frac{3\gamma A^2}{4} \right) \delta + \frac{3\gamma A^2}{4} \delta^*$$

We observe that the output phasor at frequency ω is not just proportional to the input phasor δ at frequency ω but has distinct contributions to both δ and δ^*

→ Linearization is not analytic

In Fourier domain, we have:

$$\frac{\Delta \hat{Y}(\omega)}{\Delta \hat{X}(\omega)} \left(\frac{\alpha}{2} + \frac{3\gamma A^2}{4} \right) \delta + \frac{3\gamma A^2}{4} e^{-2j\text{Phase}(\delta)}$$

PHD Derivation

$$\begin{aligned} B_{pm} &= K_{pm} (|A_{11}|) P^{+m} \\ &+ \sum_{qn} G_{pq,mn} (|A_{11}|) P^{+m} \operatorname{Re}(A_{qn} P^{-n}) \\ &+ \sum_{qn} H_{pq,mn} (|A_{11}|) P^{+m} \operatorname{Im}(A_{qn} P^{-n}) \end{aligned}$$

in which

$$K_{pm} (|A_{11}|) = F_{pm} (|A_{11}|, 0, \dots, 0)$$

$$G_{pq,mn} (|A_{11}|) = \left. \frac{\partial F_{pm}}{\partial \operatorname{Re}(A_{qn} P^{-n})} \right|_{|A_{11}|, 0, \dots, 0}$$

$$H_{pq,mn} (|A_{11}|) = \left. \frac{\partial F_{pm}}{\partial \operatorname{Im}(A_{qn} P^{-n})} \right|_{|A_{11}|, 0, \dots, 0}$$

**Spectral mapping
is nonanalytic**

PHD Derivation

Since

$$\operatorname{Re}(A_{qn}P^{-n}) = \frac{A_{qn}P^{-n} + \operatorname{conj}(A_{qn}P^{-n})}{2}$$

$$\operatorname{Im}(A_{qn}P^{-n}) = \frac{A_{qn}P^{-n} - \operatorname{conj}(A_{qn}P^{-n})}{2j}$$

we get

$$\begin{aligned} B_{pm} &= K_{pm} (|A_{11}|) P^{+m} \\ &+ \sum_{qn} G_{pq,mn} (|A_{11}|) P^{+m} \left(\frac{A_{qn}P^{-n} + \operatorname{conj}(A_{qn}P^{-n})}{2} \right) \\ &+ \sum_{qn} H_{pq,mn} (|A_{11}|) P^{+m} \left(\frac{A_{qn}P^{-n} - \operatorname{conj}(A_{qn}P^{-n})}{2j} \right) \end{aligned}$$

PHD Model

$$B_{pm} = X_{pm}^{(FB)}(|A_{11}|)P^{+m} + \sum_{qn} X_{pq,mn}^{(S)}(|A_{11}|)P^{+m-n}A_{qn} \\ + \sum_{qn} X_{pq,mn}^{(T)}(|A_{11}|)P^{+m+n}\text{conj}(A_{qn})$$

**PHD
Model Equation**

$$X_{p1,m1}^{(S)}(|A_{11}|) = \frac{K_{pm}(|A_{11}|)}{|A_{11}|} \quad X_{p1,m1}^{(T)}(|A_{11}|) = 0$$

$$\forall \{q,n\} \neq \{1,1\} : X_{pq,mn}^{(S)}(|A_{11}|) = \frac{G_{pq,mn}(|A_{11}|) - jH_{pq,mn}(|A_{11}|)}{2}$$

$$\forall \{q,n\} \neq \{1,1\} : X_{pq,mn}^{(T)}(|A_{11}|) = \frac{G_{pq,mn}(|A_{11}|) + jH_{pq,mn}(|A_{11}|)}{2}$$

1-Tone X-Parameter Formalism*

Approximates

Incident Waves

Scattered Waves

$$B_{p,k} = X_{p,k}^{(FB)}(|A_{1,1}|, A_{1,2}P^{-2}, A_{1,3}P^{-3}, \dots)$$

Nonlinear Mapping

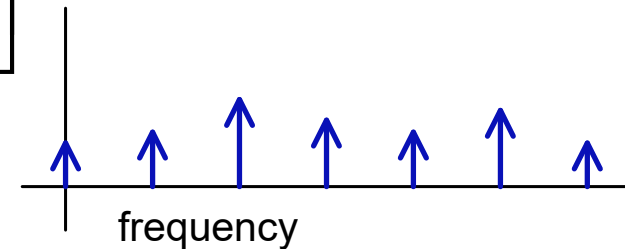
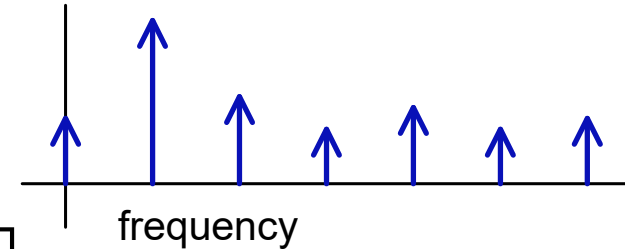
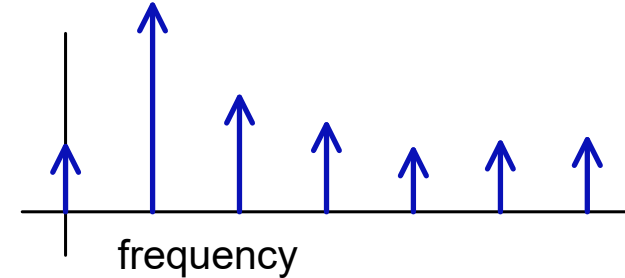
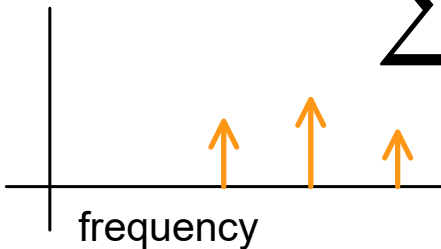
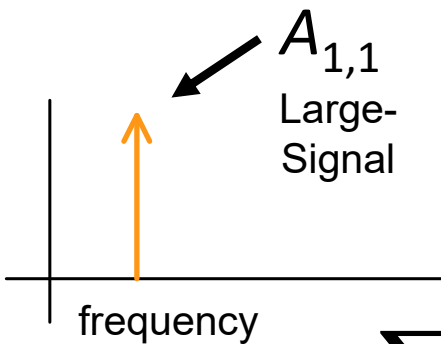
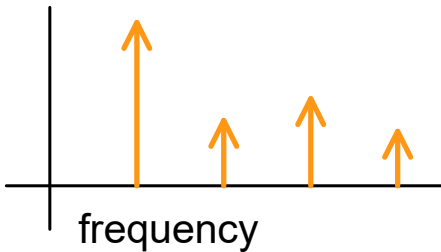
\approx

$$X_{p,k}^{(FB)}(|A_{1,1}|, 0, 0, \dots)$$

Simple Nonlinear Mapping

$$\sum \left[X_{p,k;q,l}^{(S)} \cdot A_{q,l} + X_{p,k;q,l}^{(T)} \cdot A_{q,l}^* \right]$$

Nonanalytic Harmonic Superposition

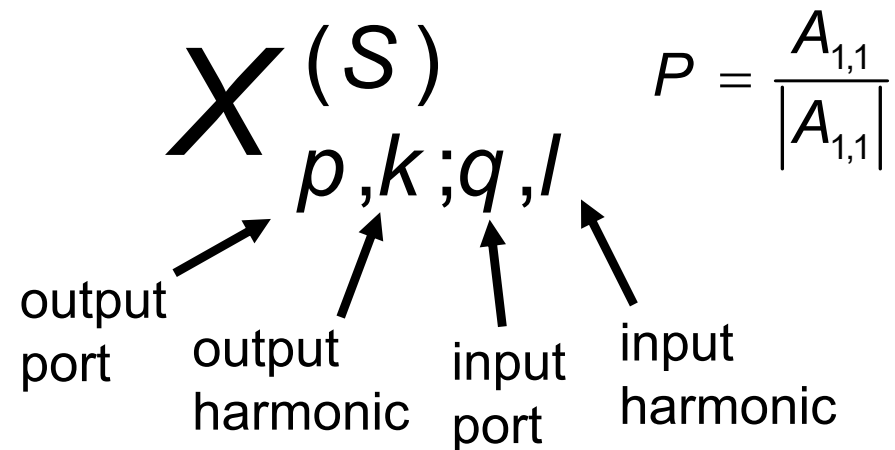


*J. Verspecht, *et al.*, "Linearization...", 2005.

1-Tone X-Parameter Formalism*

$$B_{p,k} \approx \underbrace{X_{p,k}^{(FB)} \cdot P^k}_{\text{Simple nonlinear map}} + \underbrace{\sum_{\substack{q=1, l=1 \\ (q,l) \neq (1,1)}}^{q=N, l=K} X_{p,k;q,l}^{(S)} \cdot A_{q,l} \cdot P^{k-l}}_{\text{Linear harmonic map function of incident wave}} + \underbrace{\sum_{\substack{q=1, l=1 \\ (q,l) \neq (1,1)}}^{q=N, l=K} X_{p,k;q,l}^{(T)} \cdot A_{q,l}^* \cdot P^{k+l}}_{\text{Linear harmonic map function of conjugate of incident wave}}$$

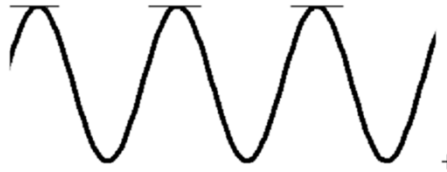
- X-parameters of type FB, S, and T fully characterize the nonlinear function.
- Depend on
 - frequency
 - large signal magnitude, $|A_{1,1}|$
 - DC bias



*D. E. Root, *et al.*, *X-Parameters*, 2013.

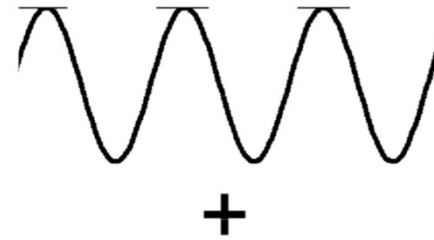
Excitation Design

Excitation 1

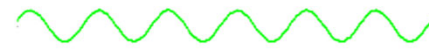


Fundamental - f

Excitation 2



Fundamental - f



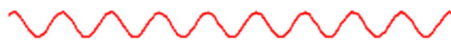
2nd harmonic - $2f$

Excitation 3



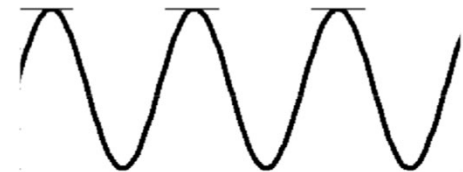
Fundamental - f

+



3rd harmonic - $3f$

Excitation 4



Fundamental - f

+



4th harmonic - $4f$

Each excitation will generate response with fundamental and all harmonics

X-Parameter Data File

TOP: FILE DESCRIPTION

! Created Fri Jul 30 07:44:48 2010

! Version = 2.0

! HB_MaxOrder = 25

! XParamMaxOrder = 12

! NumExtractedPorts = 3

! IDC_1=0 NumPts=1

! IDC_2=0 NumPts=1

! VDC_3=12 NumPts=1

! ZM_2_1=50 NumPts=1

! ZP_2_1=0 NumPts=1

! AN_1_1=100e-03(20.000000dBm) NumPts=1

! fund_1=[100 Hz->1 GHz] NumPts=4

X-Parameter Data File

MIDDLE: FORMAT DESCRIPTION

BEGIN XParamData

```
% fund_1(real) FV_1(real) FV_2(real) FI_3(real) FB_1_1(complex)
% FB_1_2(complex) FB_1_3(complex) FB_1_4(complex)
% FB_1_7(complex) FB_1_8(complex) FB_1_9(complex)
% FB_1_12(complex) FB_2_1(complex) FB_2_2(complex)
% FB_2_5(complex) FB_2_6(complex) FB_2_7(complex)
% FB_2_10(complex) FB_2_11(complex) FB_2_12(complex)
% T_1_1_1_1(complex) S_1_2_1_1(complex) T_1_2_1_1(complex)
% S_1_4_1_1(complex) T_1_4_1_1(complex) S_1_5_1_1(complex)
% T_1_6_1_1(complex) S_1_7_1_1(complex) T_1_7_1_1(complex)
% S_1_9_1_1(complex) T_1_9_1_1(complex) S_1_10_1_1(complex))
% T_1_11_1_1(complex) S_1_12_1_1(complex) T_1_12_1_1(complex)
% T_2_1_1_1(complex) S_2_2_1_1(complex) T_2_2_1_1(complex)
% S_2_4_1_1(complex) T_2_4_1_1(complex) S_2_5_1_1(complex
% T_2_6_1_1(complex) S_2_7_1_1(complex) T_2_7_1_1(complex)
% S_2_9_1_1(complex) T_2_9_1_1(complex) S_2_10_1_1(complex)
```


X-Parameter Data File

BOTTOM: DATA LISTING

| | | | | | |
|--------------|--------------|--------------|--------------|--------------|--------------|
| 100 | 0 | 0.903921 | 0.0263984 | 0.316228 | -5.41159e-09 |
| -5.8503e-16 | -4.19864e-10 | -6.37642e-16 | -1.6748e-10 | -4.62314e-16 | |
| -1.25093e-15 | -3.79264e-10 | -7.91128e-16 | -1.51261e-10 | 1.93535e-17 | |
| -1.38032e-16 | -2.09262e-10 | 0.107122 | -5.52212e-08 | 0.0739648 | |
| -0.0081633 | -2.40901e-08 | -0.00739395 | -1.21199e-08 | -0.000530768 | |
| 0.000921039 | -4.82427e-09 | -0.00230559 | 1.07836e-08 | -0.00288533 | |
| -1.20792e-15 | -5.09916e-10 | -6.95799e-15 | -2.56672e-09 | -3.25033e-15 | |
| -1.2948e-14 | 3.97284e-10 | -7.08201e-15 | -2.17127e-09 | -1.43757e-14 | |
| 3.39598e-15 | 3.66098e-10 | -1.08395e-14 | -4.05911e-09 | 1.67366e-14 | |
| 2.76565e-14 | 5.60242e-09 | 2.69755e-14 | -6.60802e-10 | 3.99868e-14 | |

Remarks

- Data is measured or generated from a harmonic balance simulator
- Data file can be very large

X-Parameter Relationship

$$b_{ik} = D_{ik} (|a_{11}|) P^k + \sum_{(j,l) \neq (1,1)} \left[S_{ik,jl} (|a_{11}|) P^{k-l} a_{jl} + T_{ik,jl} (|a_{11}|) P^{k+l} a_{jl}^* \right]$$

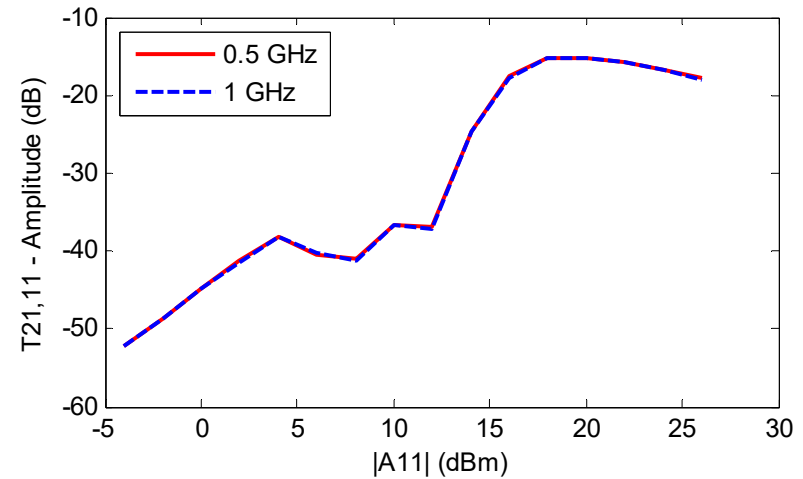
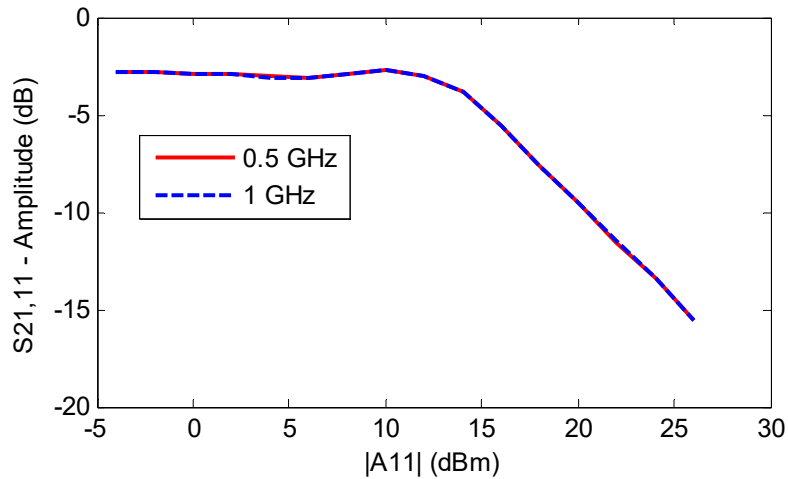
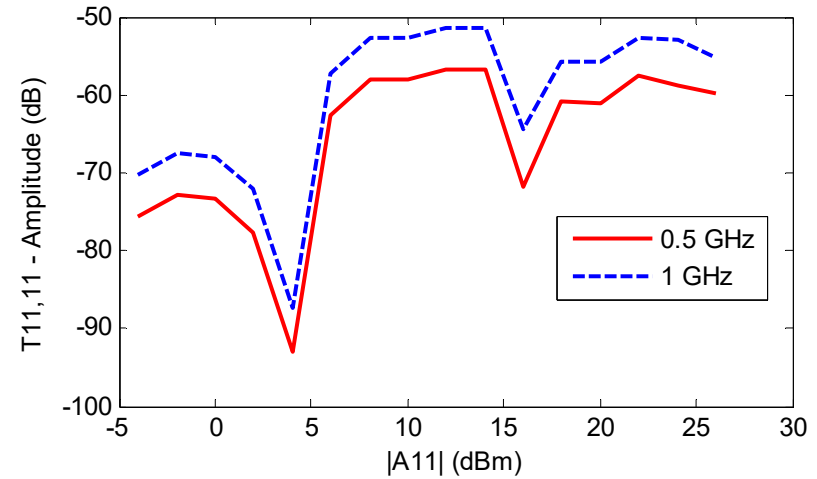
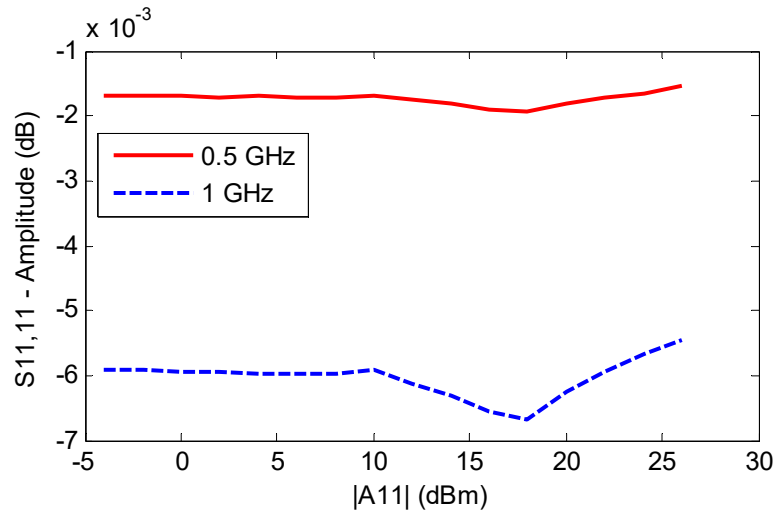
P : Phase of a_{11}

D_{ik} : B – type X parameter

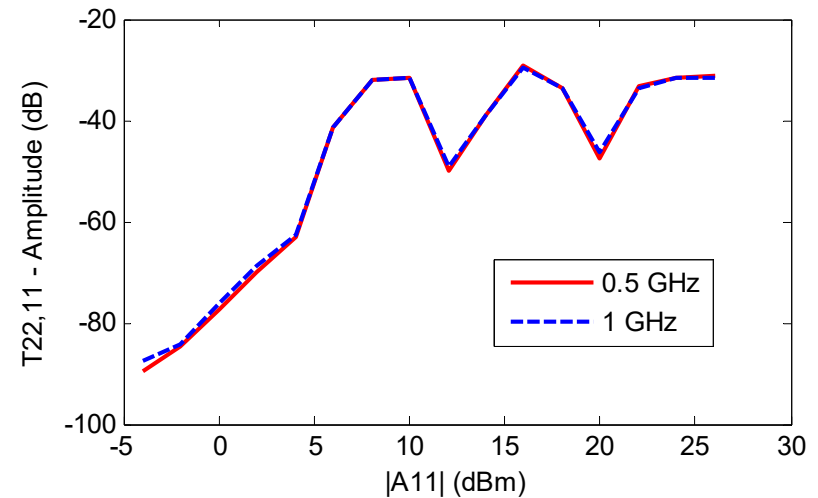
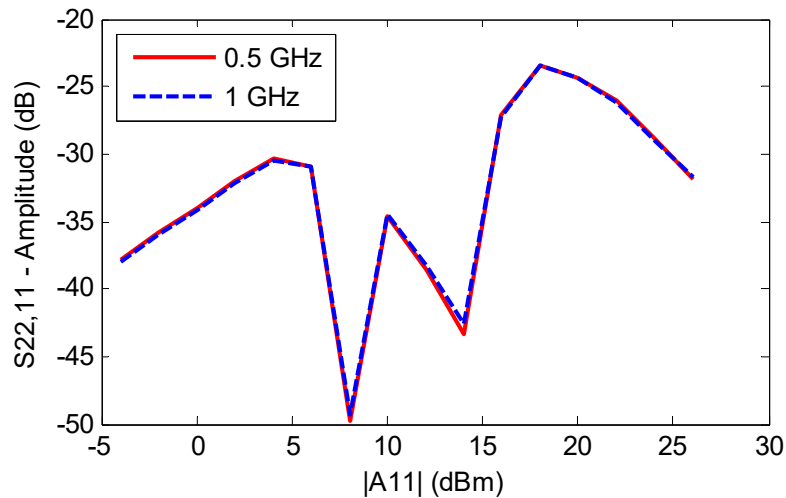
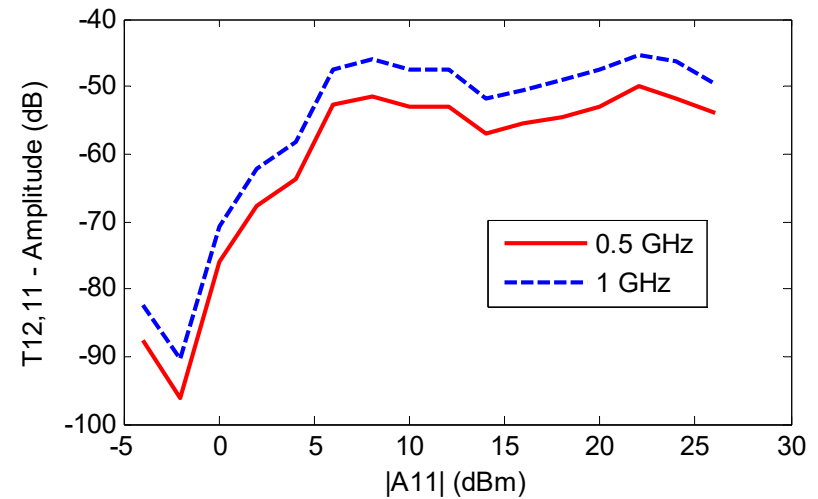
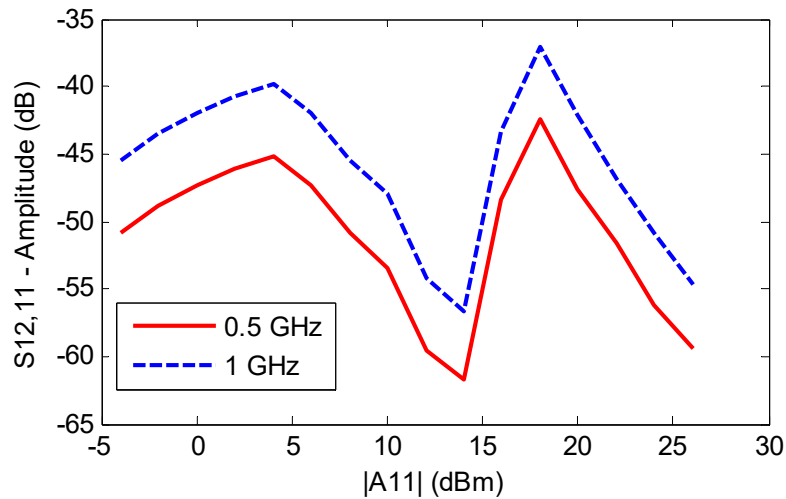
$S_{ik,jl}$: S – type X parameter

$T_{ik,jl}$: T – type X parameter

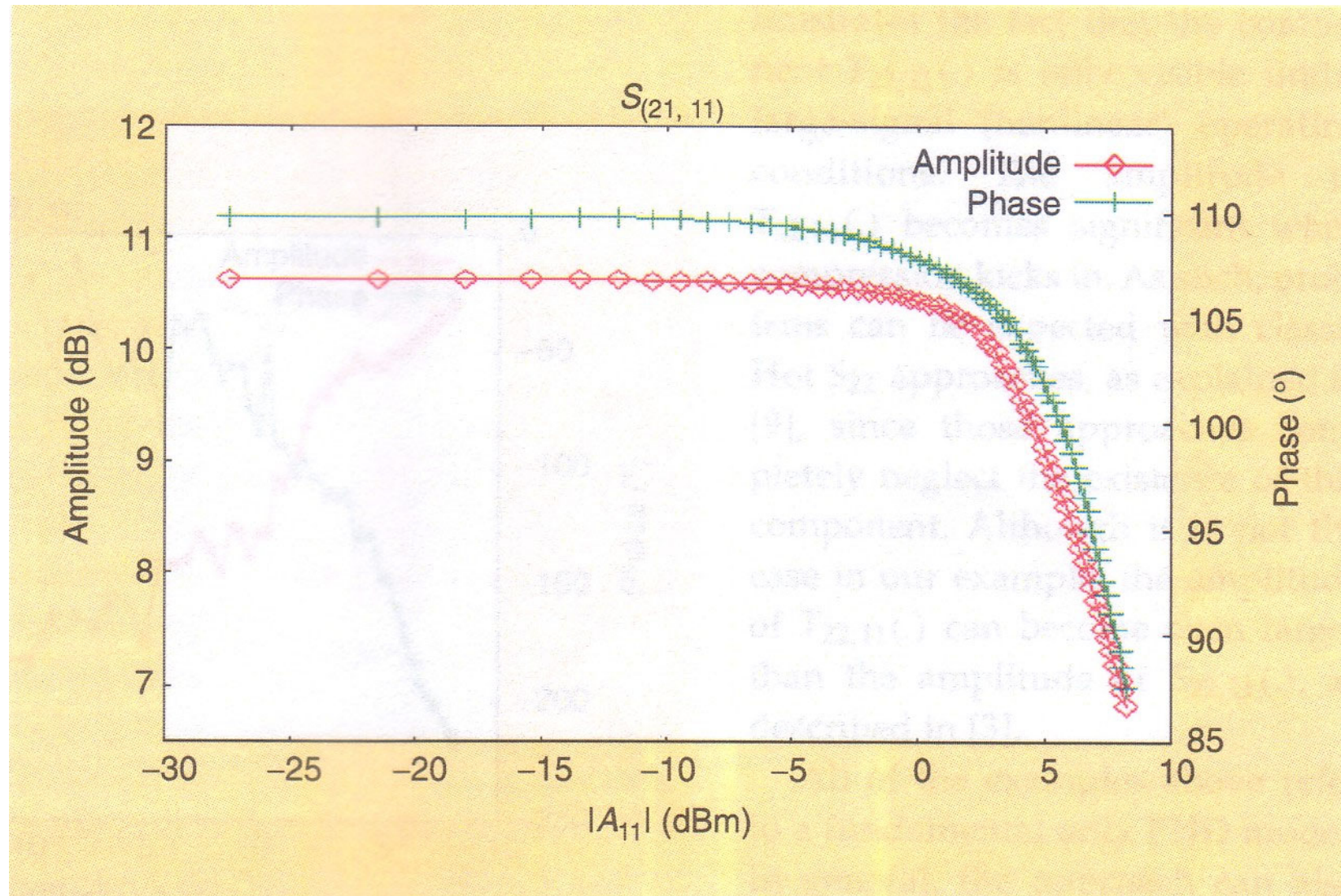
X Parameters of CMOS



X Parameters of CMOS

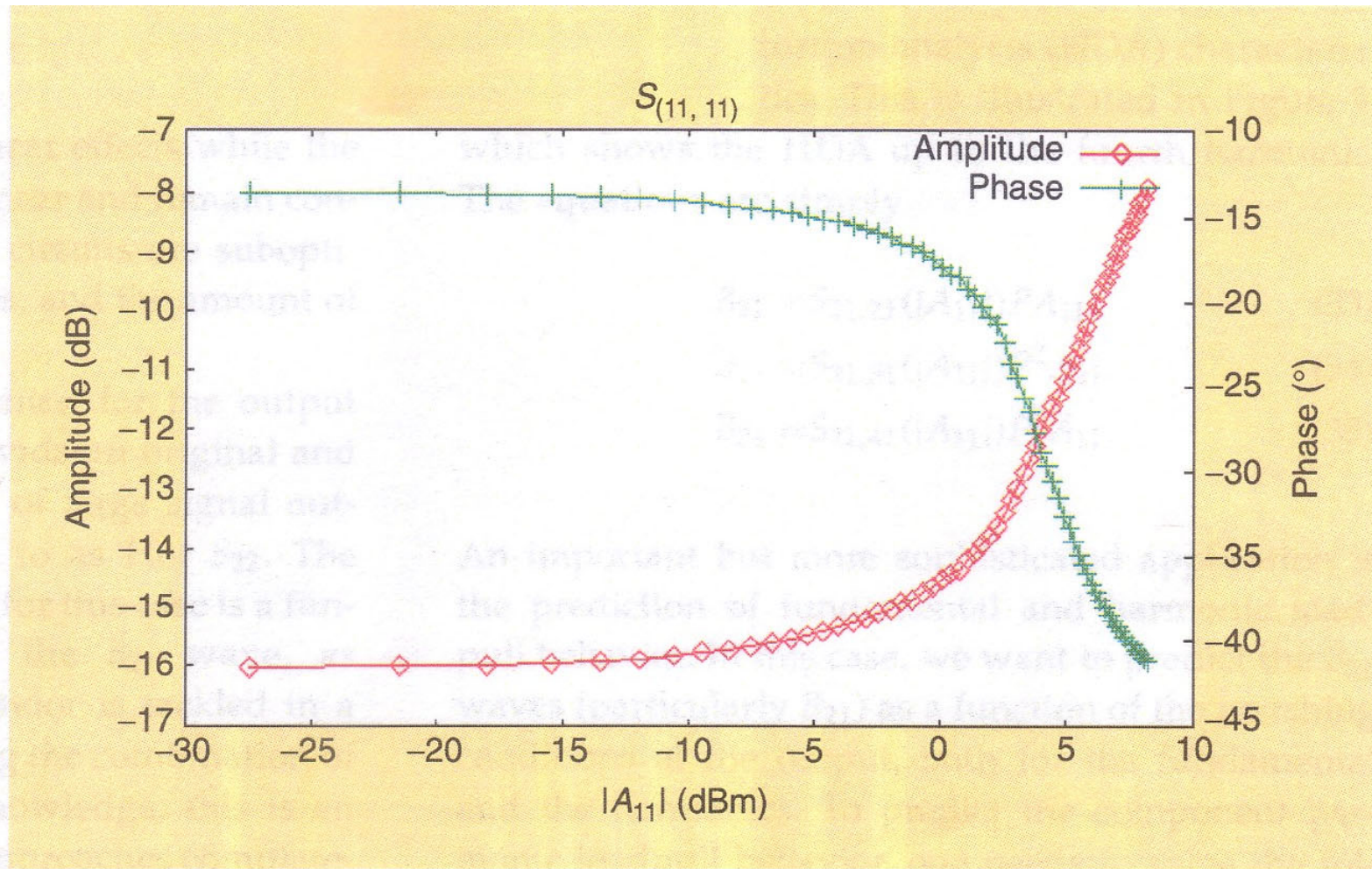


Large-Signal Reflection



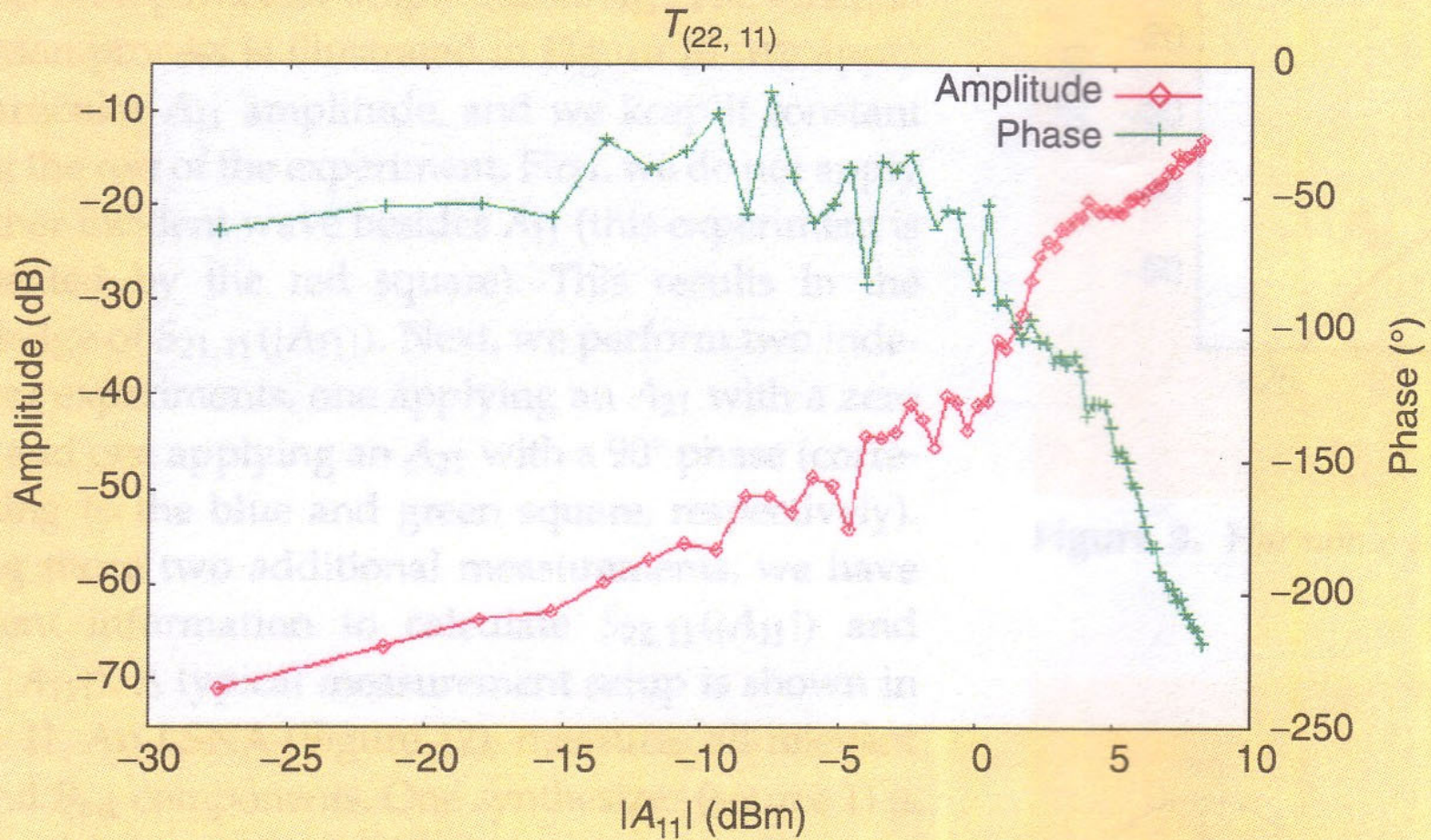
Microwave amplifier with fundamental frequency at 9.9 GHz

Compression and AM-PM



Microwave amplifier with fundamental frequency at 9.9 GHz

$T_{22,11}$



Microwave amplifier with fundamental frequency at 9.9 GHz

Special Terms

- **T-Type X Parameter**
 - Spectral mapping is non-analytical
 - Real and imaginary parts in FD are treated differently
 - Even and odd parts in TD are treated differently
 - T involves non-causal component of signal
- **Phase Term P**
 - P is phase of large-signal excitation (a_{11})
 - Contributions to B waves will depend on P
 - In measurements, system must be calibrated for phase

Notation Change

Define

$$S_{ik,jl}(|a_{11}|) = X_{ik,jl}^{(S)}(|A_{11}|)$$

$$T_{ik,jl}(|a_{11}|) = X_{ik,jl}^{(T)}(|A_{11}|)$$

$$D_{ik}(|a_{11}|) = X_{ik}^{(FB)}(|a_{11}|)$$

Handling Phase Term

$$b_{ik} = D_{ik} (|a_{11}|) P^k + \sum_{(j,l) \neq (1,1)} \left[S_{ik,jl} (|a_{11}|) P^{k-l} a_{jl} + T_{ik,jl} (|a_{11}|) P^{k+l} a_{jl}^* \right]$$

Multiply through by P^{-k}

$$b_{ik} P^{-k} = D_{ik} (|a_{11}|) + \sum_{(j,l) \neq (1,1)} \left[S_{ik,jl} (|a_{11}|) P^{-l} a_{jl} + T_{ik,jl} (|a_{11}|) P^{+l} a_{jl}^* \right]$$

$$P = e^{j\phi_{11}} \quad \text{where } \phi_{11} \text{ is the phase of } a_{11}$$

we can always express the relationship in terms of modified power wave variables

$$\bar{b}_{ik} = D_{ik} (|a_{11}|) + \sum_{(j,l) \neq (1,1)} \left[S_{ik,jl} (|a_{11}|) \bar{a}_{jl} + T_{ik,jl} (|a_{11}|) \bar{a}_{jl}^* \right]$$

$$\text{where } \bar{b}_{ik} = b_{ik} P^{-k} \quad \text{and} \quad \bar{a}_{ik} = a_{ik} P^{-k}$$

Handling R&I Components

Because of non-analytical nature of spectral mapping, real and imaginary component interactions must be accounted for separately.

we have

$$\begin{pmatrix} b_r \\ b_i \end{pmatrix} = \begin{pmatrix} X_{rr} & X_{ri} \\ X_{ir} & X_{ii} \end{pmatrix} \begin{pmatrix} a_r \\ a_i \end{pmatrix}$$

where

$$X_{rr} = (S_r + T_r), \quad X_{ri} = -(S_i - T_i)$$

$$X_{ir} = (S_i + T_i), \quad X_{ii} = (S_r - T_r)$$

Handling Phase Term

Phase term can be accounted for by applying following transformations

$$\begin{pmatrix} b_r \\ b_i \end{pmatrix} = \begin{pmatrix} X_{rr} & X_{ri} \\ X_{ir} & X_{ii} \end{pmatrix} \begin{pmatrix} a_r \\ a_i \end{pmatrix}$$

$$\begin{pmatrix} \cos \theta_b & -\sin \theta_b \\ -\sin \theta_b & \cos \theta_b \end{pmatrix} \begin{pmatrix} b'_r \\ b'_i \end{pmatrix} = \begin{pmatrix} X_{rr} & X_{ri} \\ X_{ir} & X_{ii} \end{pmatrix} \begin{pmatrix} \cos \theta_a & -\sin \theta_a \\ -\sin \theta_a & \cos \theta_a \end{pmatrix} \begin{pmatrix} a'_r \\ a'_i \end{pmatrix}$$

in which

$$\begin{pmatrix} b_r \\ b_i \end{pmatrix} = \begin{pmatrix} \cos \theta_b & -\sin \theta_b \\ -\sin \theta_b & \cos \theta_b \end{pmatrix} \begin{pmatrix} b'_r \\ b'_i \end{pmatrix}$$

$$\begin{pmatrix} a_r \\ a_i \end{pmatrix} = \begin{pmatrix} \cos \theta_a & -\sin \theta_a \\ -\sin \theta_a & \cos \theta_a \end{pmatrix} \begin{pmatrix} a'_r \\ a'_i \end{pmatrix}$$

X Matrix Construction

- Separate real and imaginary components
- Account for real-imaginary interactions
- Account for harmonic-to-harmonic contributions
- Account for harmonic-to-DC contributions

Matrix size is $2mn \times 2mn$

m : number of harmonics

n : number of ports

Matrix Formulation*

size: $2mn$

$$\mathbf{a} = \begin{pmatrix} \mathbf{a}_1 \\ \mathbf{a}_2 \\ \mathbf{a}_p \\ \mathbf{a}_n \end{pmatrix}$$

$$\mathbf{a}_p =$$

$$\begin{pmatrix} a_{pr}^{(1)} \\ a_{pi}^{(1)} \\ a_{pr}^{(2)} \\ a_{pi}^{(2)} \\ \cdot \\ \cdot \\ a_{pr}^{(m)} \\ a_{pi}^{(m)} \end{pmatrix}$$

We wish to use:

$$\mathbf{b} = \mathbf{X}\mathbf{a}$$

$$\mathbf{b} = \begin{pmatrix} \mathbf{b}_1 \\ \mathbf{b}_2 \\ \mathbf{b}_p \\ \mathbf{b}_n \end{pmatrix}$$

$$\mathbf{b}_p =$$

$$\begin{pmatrix} b_{pr}^{(1)} \\ b_{pi}^{(1)} \\ b_{pr}^{(2)} \\ b_{pi}^{(2)} \\ \cdot \\ \cdot \\ b_{pr}^{(m)} \\ b_{pi}^{(m)} \end{pmatrix}$$

size: $2mn$

← vector size is $2m$

m : number of harmonics

n : number of ports

(real vectors)

*DC term not included

Matrix Formulation*

$$\mathbf{X} = \begin{pmatrix} \mathbf{X}_{11} & \mathbf{X}_{12} & \cdot & \mathbf{X}_{1n} \\ \mathbf{X}_{21} & \mathbf{X}_{22} & \cdot & \cdot \\ \cdot & \cdot & \mathbf{X}_{pq} & \cdot \\ \mathbf{X}_{n1} & \cdot & \cdot & \mathbf{X}_{nn} \end{pmatrix}$$

← matrix size is $2mn \times 2mn$

m : number of harmonics

n : number of ports size: $2m \times 2m$

$$\mathbf{X}_{pq} = \begin{pmatrix} X_{pqrr}^{(11)} & X_{pqri}^{(11)} & X_{pqrr}^{(12)} & X_{pqri}^{(12)} & \cdot & \cdot & X_{pqrr}^{(1m)} & X_{pqri}^{(1m)} \\ X_{pqir}^{(11)} & X_{pqii}^{(11)} & X_{pqir}^{(12)} & X_{pqii}^{(12)} & \cdot & \cdot & \cdot & \cdot \\ X_{pqrr}^{(21)} & X_{pqri}^{(21)} & X_{pqrr}^{(22)} & X_{pqri}^{(22)} & \cdot & \cdot & \cdot & \cdot \\ X_{pqir}^{(21)} & X_{pqii}^{(21)} & X_{pqir}^{(22)} & X_{pqii}^{(22)} & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ X_{pqir}^{(m1)} & X_{pqii}^{(m1)} & \cdot & \cdot & \cdot & \cdot & X_{pqir}^{(mm)} & X_{pqii}^{(mm)} \end{pmatrix}$$

(real matrix)

*DC term not included

X Matrix for 2-Port System*

(2 harmonics)

$$\mathbf{X} = \begin{pmatrix} X_{11rr}^{(11)} & X_{11ri}^{(11)} & X_{11rr}^{(12)} & X_{11ri}^{(12)} & X_{12rr}^{(11)} & X_{12ri}^{(11)} & X_{12rr}^{(12)} & X_{12ri}^{(12)} \\ X_{11ir}^{(11)} & X_{11ii}^{(11)} & X_{11ir}^{(12)} & X_{11ii}^{(12)} & X_{12ir}^{(11)} & X_{12ii}^{(11)} & X_{12ir}^{(12)} & X_{12ii}^{(12)} \\ X_{11rr}^{(21)} & X_{11ri}^{(21)} & X_{11rr}^{(22)} & X_{11ri}^{(22)} & X_{12rr}^{(21)} & X_{12ri}^{(21)} & X_{12rr}^{(22)} & X_{12ri}^{(22)} \\ X_{11ir}^{(21)} & X_{11ii}^{(21)} & X_{11ir}^{(22)} & X_{11ii}^{(22)} & X_{12ir}^{(21)} & X_{12ii}^{(21)} & X_{12ir}^{(22)} & X_{12ii}^{(22)} \\ X_{21rr}^{(11)} & X_{21ri}^{(11)} & X_{21rr}^{(12)} & X_{21ri}^{(12)} & X_{22rr}^{(11)} & X_{22ri}^{(11)} & X_{22rr}^{(12)} & X_{22ri}^{(12)} \\ X_{21ir}^{(11)} & X_{21ii}^{(11)} & X_{21ir}^{(12)} & X_{21ii}^{(12)} & X_{22ir}^{(11)} & X_{22ii}^{(11)} & X_{22ir}^{(12)} & X_{22ii}^{(12)} \\ X_{21rr}^{(21)} & X_{21ri}^{(21)} & X_{21rr}^{(22)} & X_{21ri}^{(22)} & X_{22rr}^{(21)} & X_{22ri}^{(21)} & X_{22rr}^{(22)} & X_{22ri}^{(22)} \\ X_{21ir}^{(21)} & X_{21ii}^{(21)} & X_{21ir}^{(22)} & X_{21ii}^{(22)} & X_{22ir}^{(21)} & X_{22ii}^{(21)} & X_{22ir}^{(22)} & X_{22ii}^{(22)} \end{pmatrix}$$

(real matrix)

For instance, $X_{21ri}^{(12)}$ is the contribution to the real part of the 1st harmonic of the wave scattered at port 2 due to the imaginary part of the 2nd harmonic of the wave incident port in port 1.

*DC term not included

Polyharmonic Impedance

| Linear Impedance | Polyharmonic Impedance | Nonlinear Impedance |
|--|--|--|
| <ul style="list-style-type: none"> - Time invariant - Linear - Scalar $V = ZI$ <p>FD & TD</p> | <ul style="list-style-type: none"> - Time invariant - Linear - Matrix $[V(f)] = [Z(f)][I(f)]$ <p>FD req</p> | <ul style="list-style-type: none"> - Time variant - Nonlinear - Function $V(t) = Z(I(t))$ |

Model assumes that nonlinear effects are mild and are captured via harmonic superposition.

Polyharmonic Impedance

4-harmonic system

in frequency domain:

$$\begin{bmatrix} V^{(1)} \\ V^{(2)} \\ V^{(3)} \\ V^{(4)} \end{bmatrix} = \begin{bmatrix} Z^{(11)} & Z^{(12)} & Z^{(13)} & Z^{(14)} \\ Z^{(21)} & Z^{(22)} & Z^{(23)} & Z^{(24)} \\ Z^{(31)} & Z^{(32)} & Z^{(33)} & Z^{(34)} \\ Z^{(41)} & Z^{(42)} & Z^{(43)} & Z^{(44)} \end{bmatrix} \begin{bmatrix} I^{(1)} \\ I^{(2)} \\ I^{(3)} \\ I^{(4)} \end{bmatrix}$$

in time domain:

$$v(t) = v^{(1)}(t) + v^{(2)}(t) + v^{(3)}(t) + v^{(4)}(t)$$

$$i(t) = i^{(1)}(t) + i^{(2)}(t) + i^{(3)}(t) + i^{(4)}(t)$$

Polyharmonic Impedance

\mathbf{Z}_0 : Reference impedance matrix

\mathbf{Z} : Polyharmonic impedance matrix

\mathbf{V} : Voltage vector

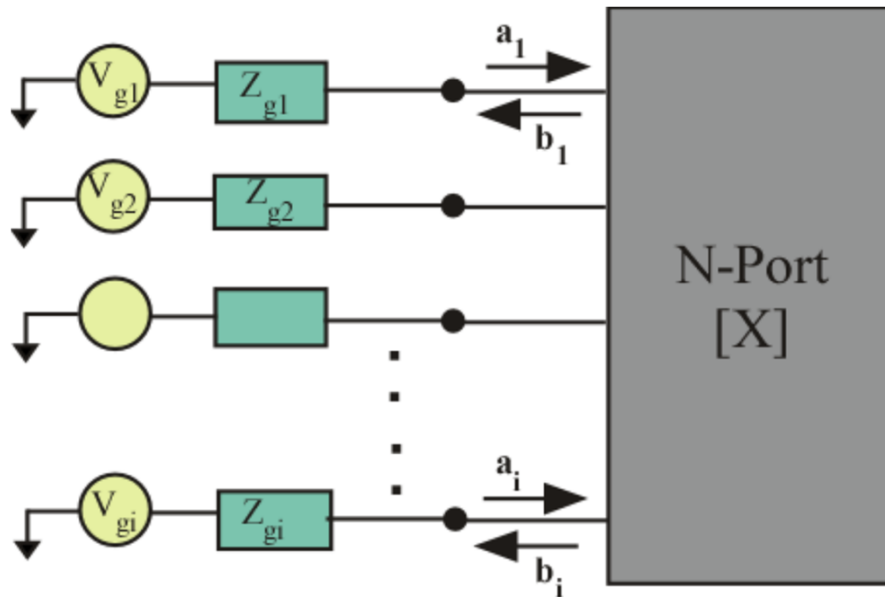
\mathbf{I} : Current vector

$$\mathbf{Z} = (\mathbf{1} + \mathbf{X})(\mathbf{1} - \mathbf{X})^{-1} \mathbf{Z}_0$$

$$\mathbf{V} = \mathbf{Z}\mathbf{I}$$

Describes interactions between harmonic components of voltage and current.

Network Formulation



Scattered waves

$$\mathbf{b} = \mathbf{X}\mathbf{a}$$

Termination equations

$$\mathbf{a} = \mathbf{D}\mathbf{v}_g + \mathbf{\Gamma}\mathbf{b}$$

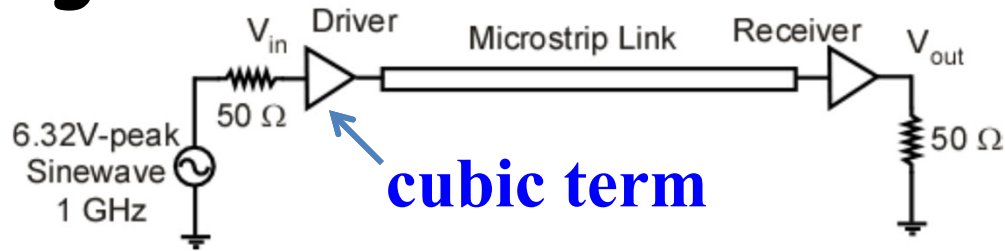
Wave Solution

$$\mathbf{a} = [\mathbf{1} - \mathbf{\Gamma}\mathbf{X}]^{-1} \mathbf{D}\mathbf{v}_g$$

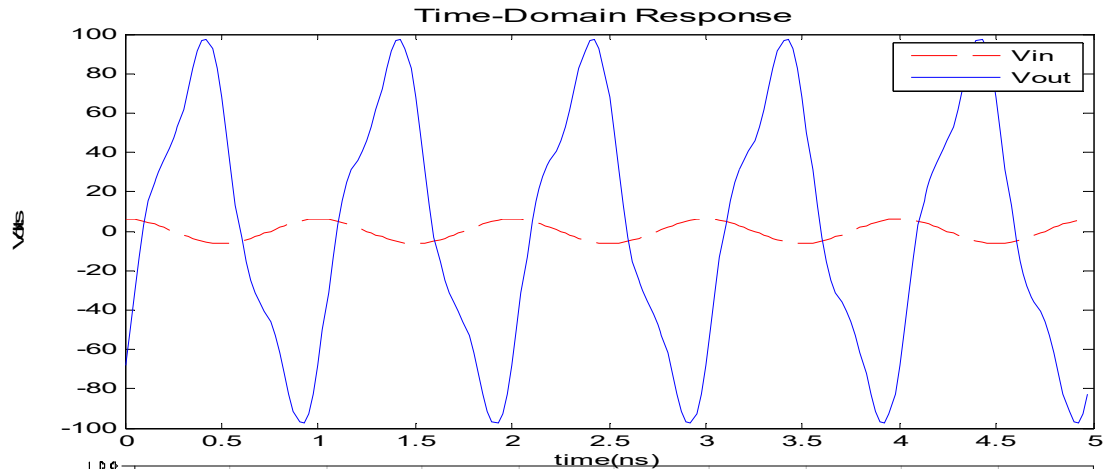
Voltage Solution

$$\mathbf{v} = (\mathbf{1} + \mathbf{X})\mathbf{a}$$

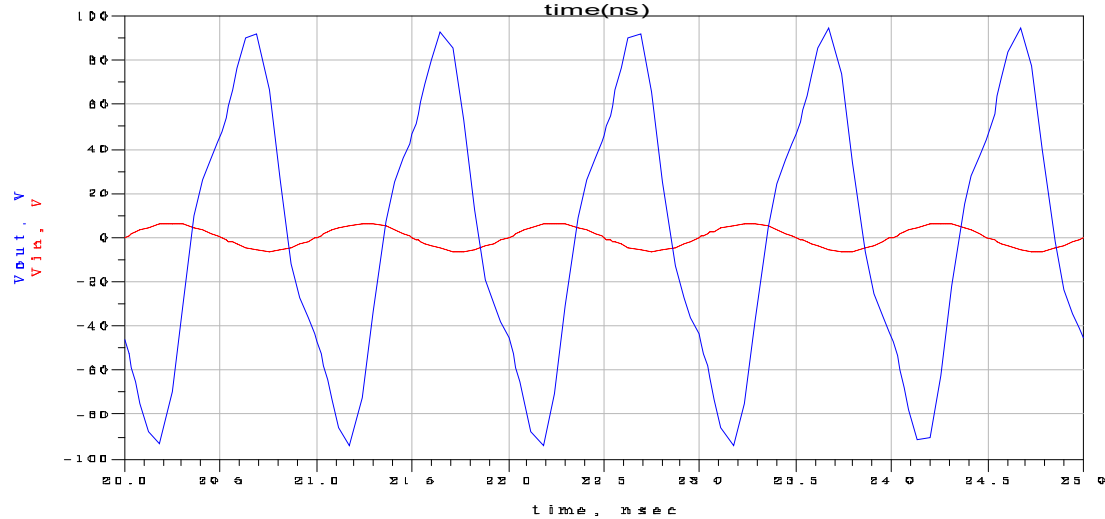
Steady-State Simulations



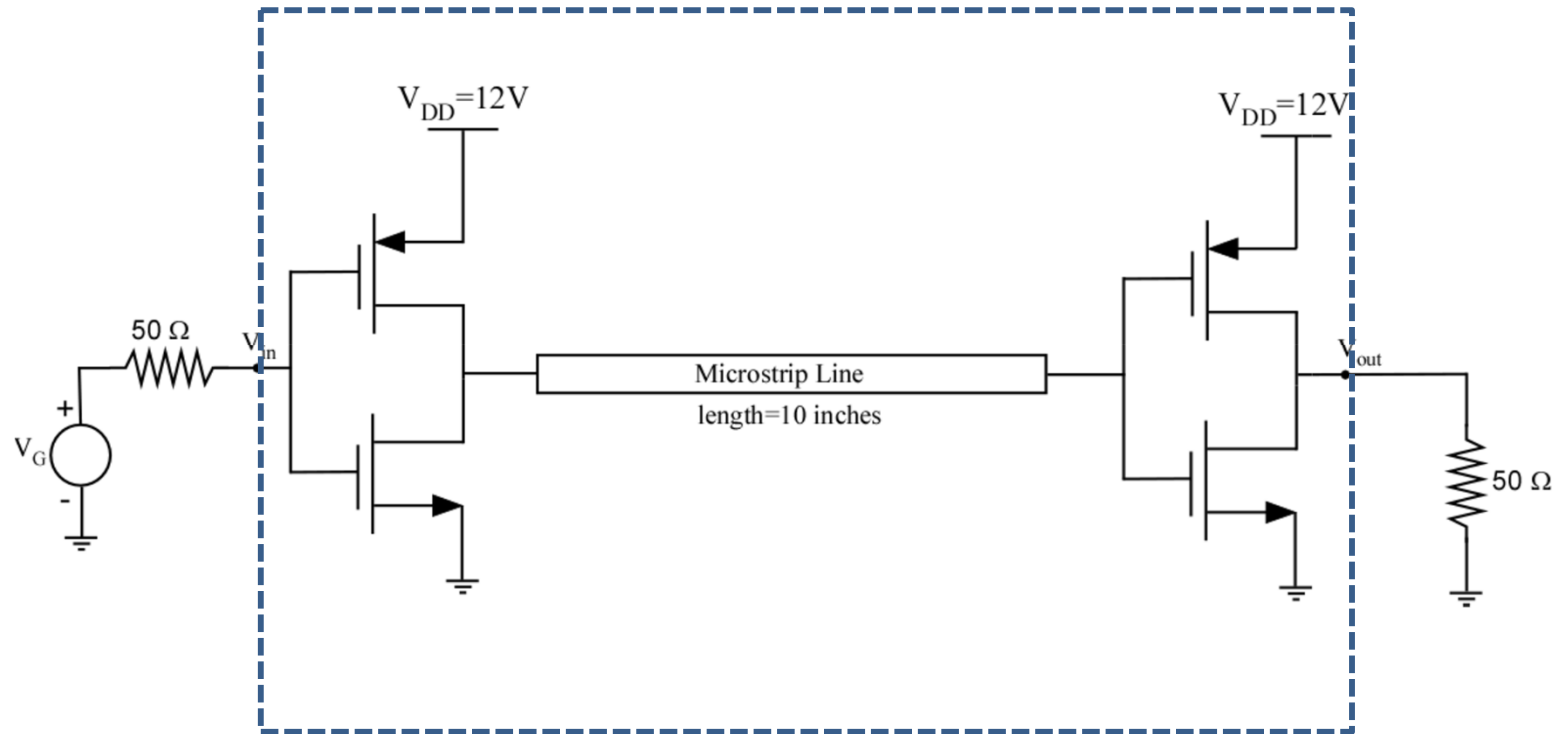
X Parameter



ADS

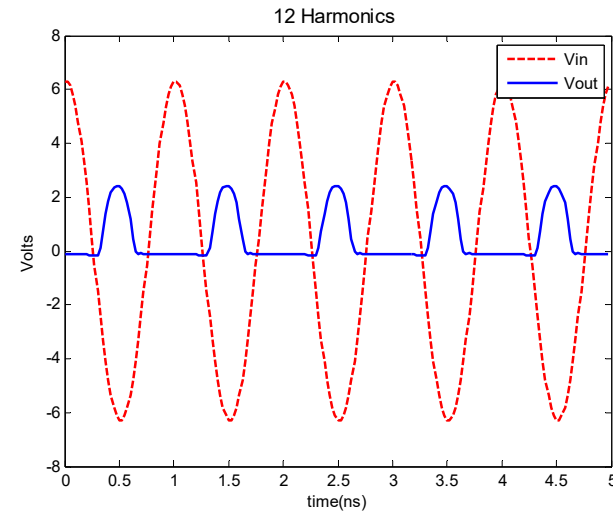
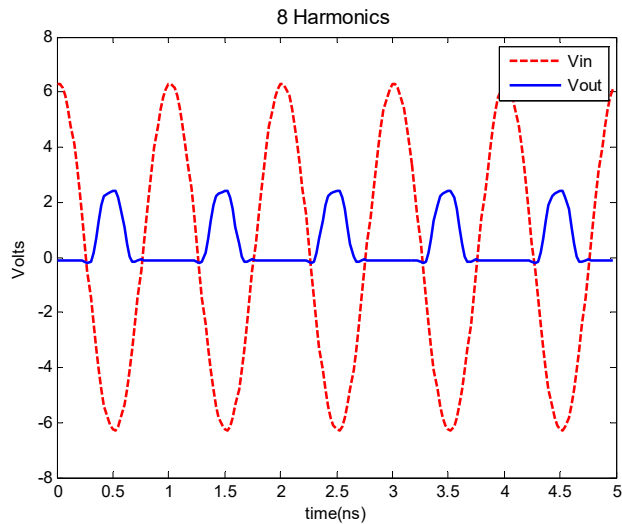
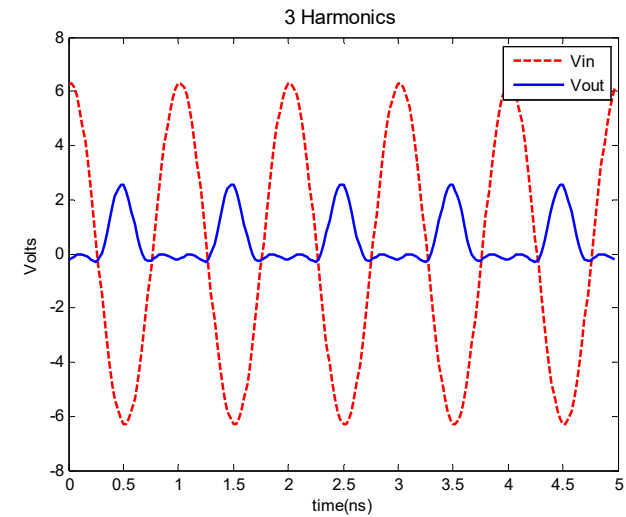
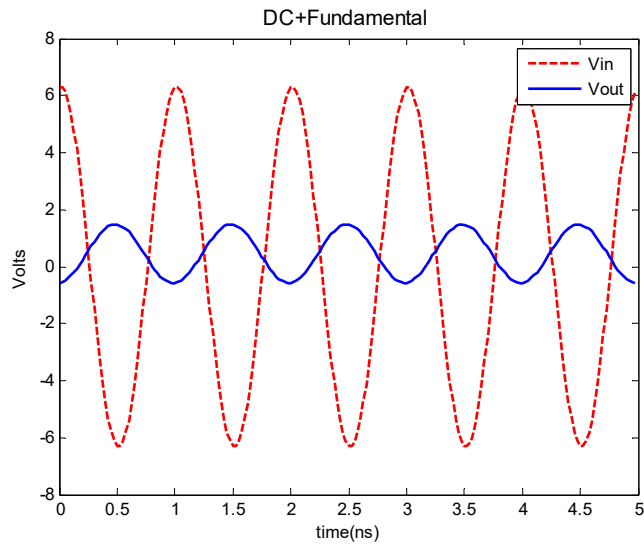


CMOS Driver/Receiver Channel

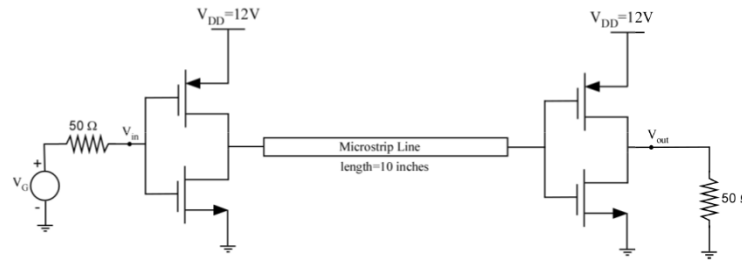


- Generate X parameters for composite system
- Power level: 20 dBm, frequency: 1 GHz
- Construct X matrix
- Combine with terminations for simulation

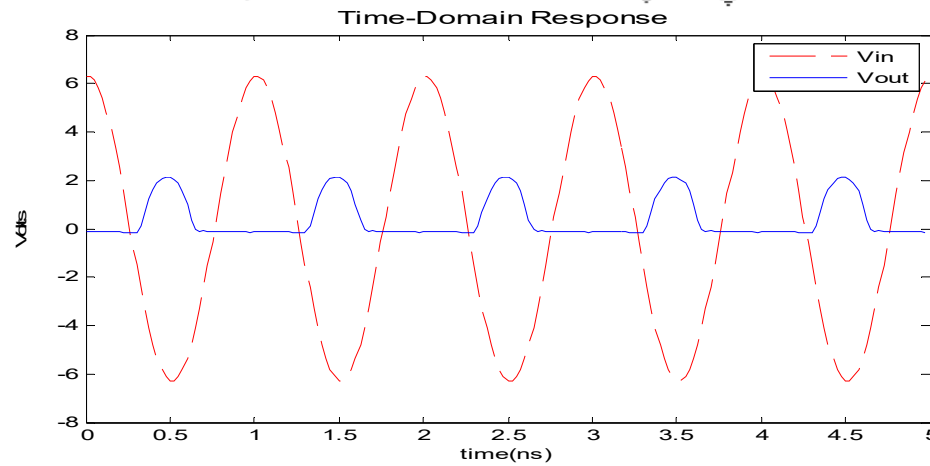
CMOS Driver/Receiver - Harmonics



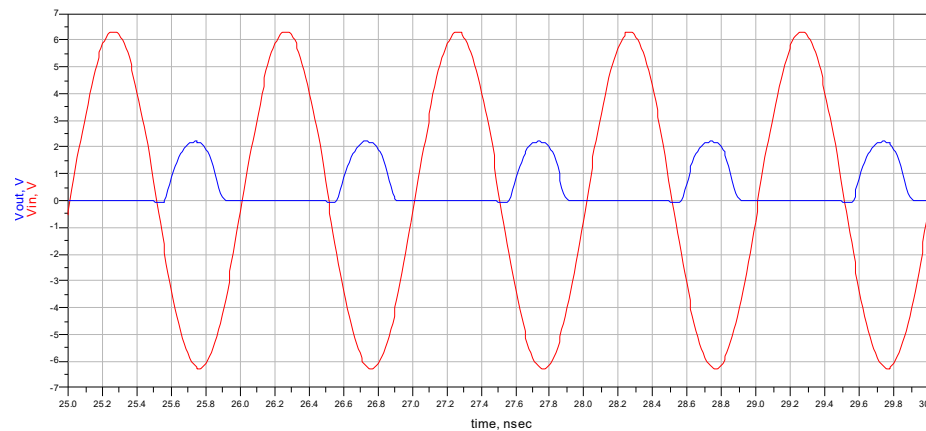
Validation



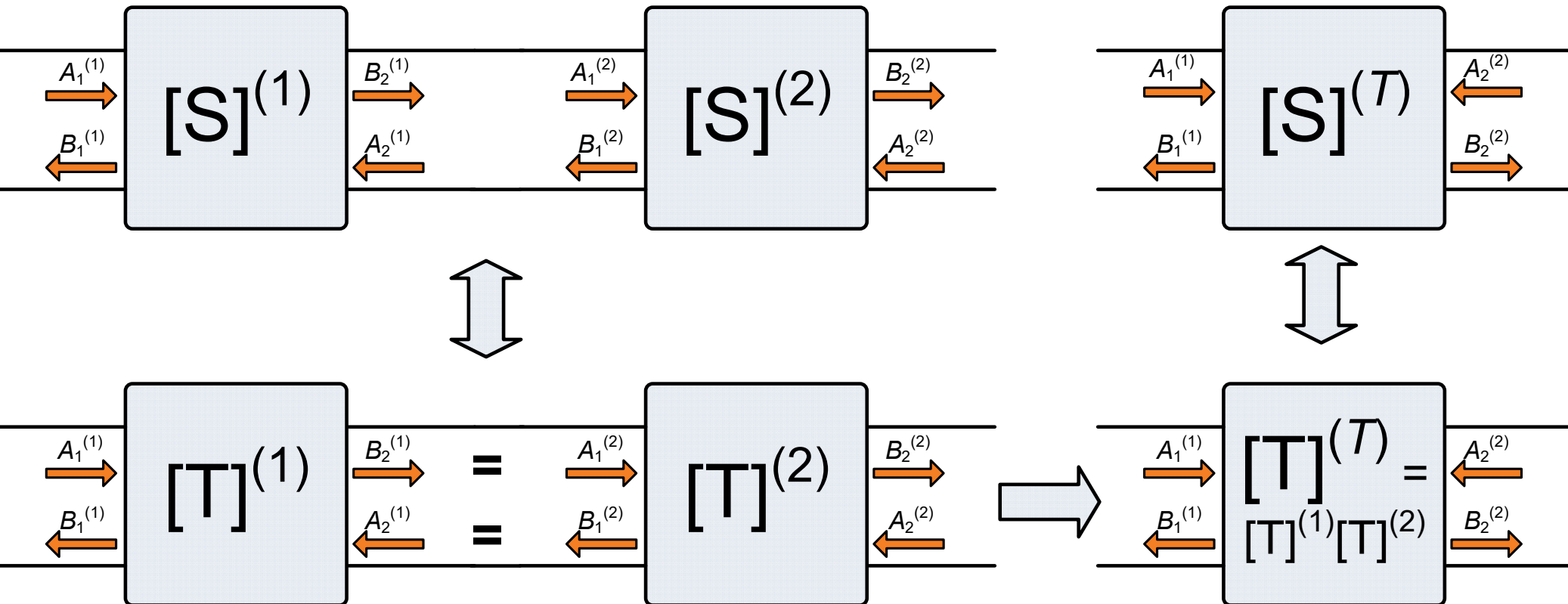
X Parameter



ADS



Cascading S-Parameter Blocks*

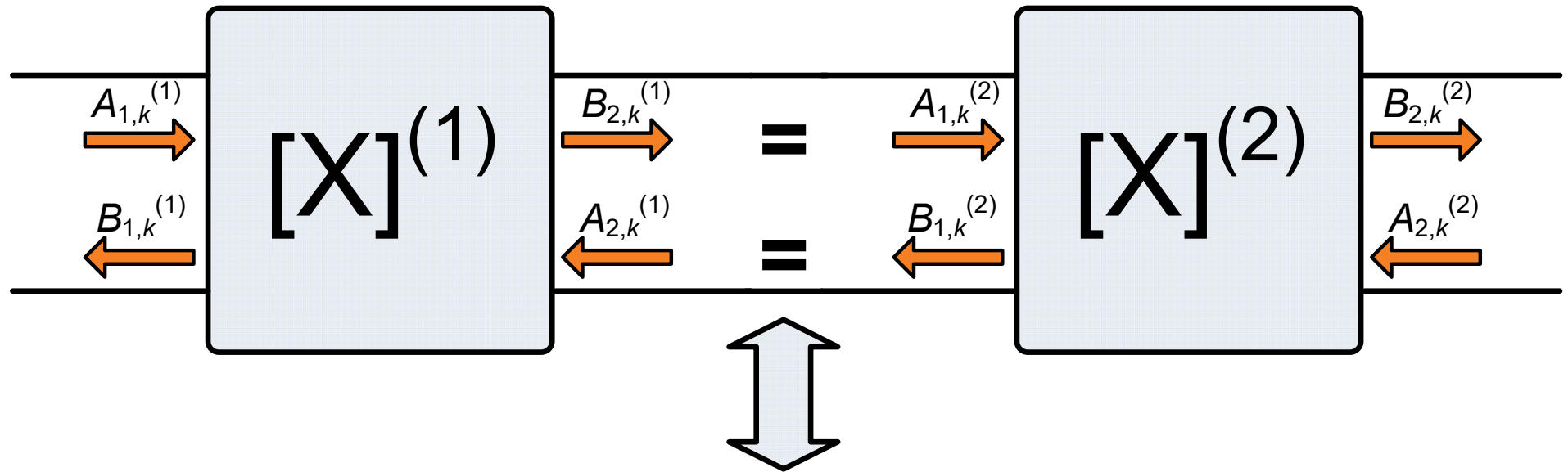


$[T]$ = transfer scattering parameters.

Can disregard circuit behavior at internal node.

*G. Gonzalez, *Microwave Transistor Amplifiers: Analysis and Design*, 2nd ed. Prentice-Hall, 1997.

Cascading X-Parameter Blocks*

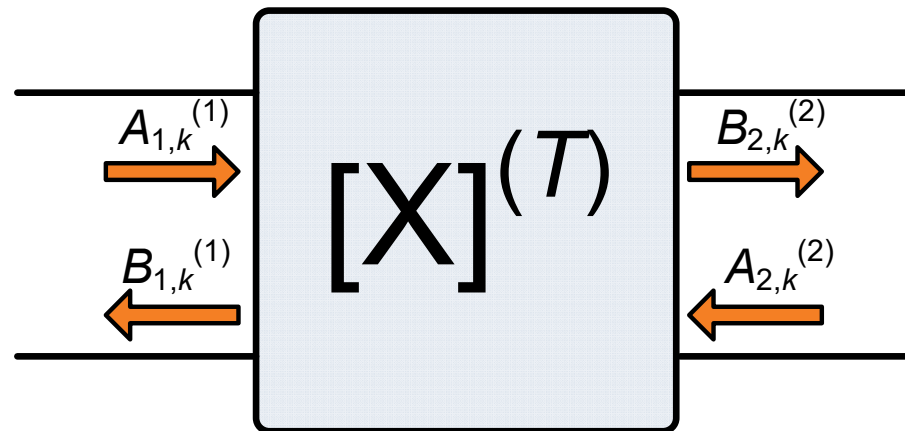


These equations at the internal node must always be satisfied:

$$B_{1,k}^{(1)} = A_{1,k}^{(2)},$$

$$A_{1,k}^{(2)} = B_{2,k}^{(1)}$$

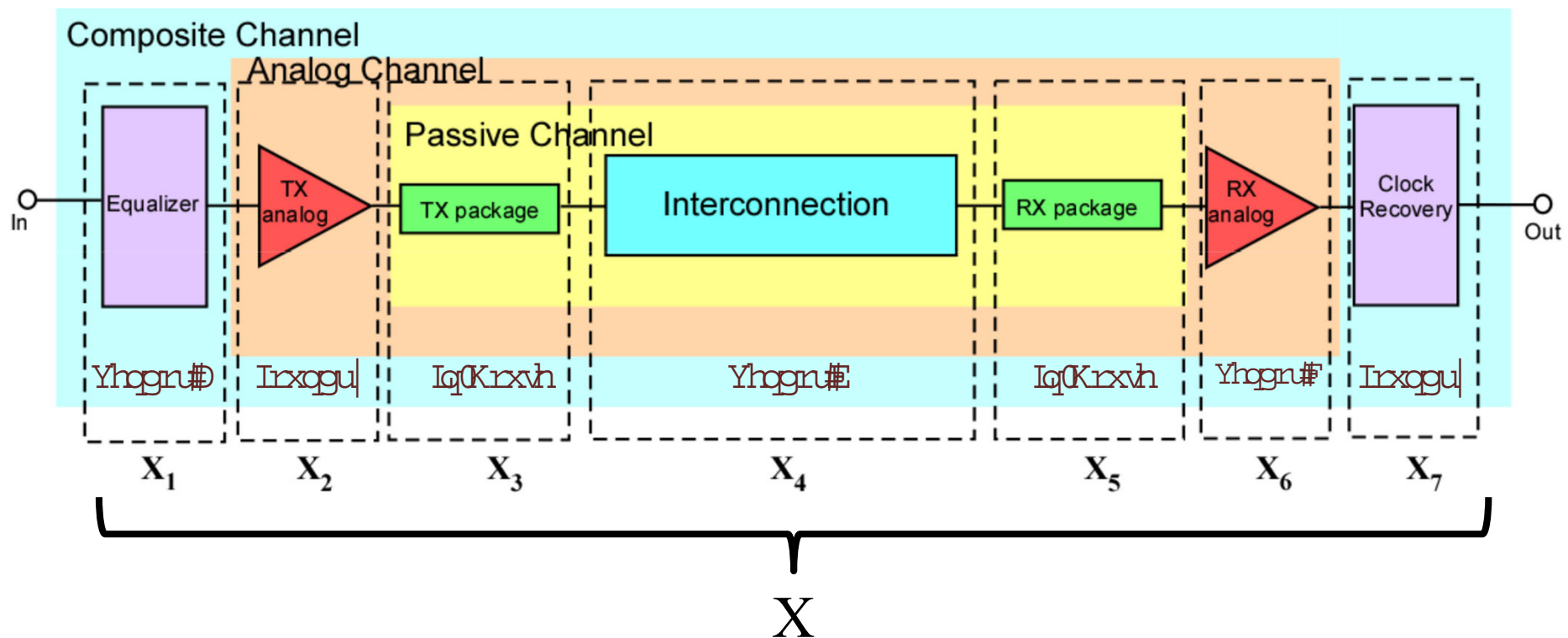
for all values of k .



*D. E. Root, *et al.*, *X-Parameters*, 2013.

Cascading X Parameters

GOAL: Simulate complete channel by combining X-parameter blocks from different sources into a single composite X matrix.



X-parameters of individual devices can be accurately cascaded within a harmonic balance simulator environment.

Volterra Series

A linear causal system with memory can be described by the convolution representation

$$y(t) = \int_{-\infty}^{+\infty} h(\sigma)x(t - \sigma)d\sigma$$

where $x(t)$ is the input, $y(t)$ is the output, and $h(t)$ the impulse response of the system.

A nonlinear system without memory can be described with a Taylor series as:

$$y(t) = \sum_{n=1}^{\infty} a_n [x(t)]^n$$

where $x(t)$ is the input and $y(t)$ is the output. The a_n are Taylor series coefficients.

Volterra Series

A Volterra series combines the above two representations to describe a nonlinear system with memory

$$y(t) = \sum_{n=1}^{\infty} \frac{1}{n!} \int_{-\infty}^{\infty} du_1 \dots \int_{-\infty}^{\infty} du_n g_n(u_1, \dots, u_n) \prod_{r=1}^n x(t - u_r)$$

$$\begin{aligned}
 y(t) = & \frac{1}{1!} \int_{-\infty}^{\infty} du_1 g_1(u_1) x(t - u_1) \leftarrow \text{impulse response} \\
 & + \frac{1}{2!} \int_{-\infty}^{\infty} du_1 \int_{-\infty}^{\infty} du_2 g_2(u_1, u_2) x(t - u_1) x(t - u_2) \leftarrow \text{higher-order impulse responses} \\
 & + \frac{1}{2!} \int_{-\infty}^{\infty} du_1 \int_{-\infty}^{\infty} du_2 \int_{-\infty}^{\infty} du_3 g_3(u_1, u_2, u_3) x(t - u_1) x(t - u_2) g_2(u_1, u_2) x(t - u_1) x(t - u_2) x(t - u_3) \\
 & + \dots
 \end{aligned}$$

where $x(t)$ is the input and $y(t)$ is the output and the $g_n(u_1, \dots, u_n)$ are called the *Volterra kernels*

Volterra Series

Application to X parameters:

Take order = 2

$$y(t) = \frac{1}{1!} \int_{-\infty}^{+\infty} du_1 g_1(u_1) x(t-u_1) + \frac{1}{2!} \int_{-\infty}^{+\infty} du_1 \int_{-\infty}^{+\infty} du_2 g_2(u_1, u_2) x(t-u_1) x(t-u_2)$$

where the input $x(t)$ is given by

$$x(t) = \exp(j\omega_1 t) + \exp(j\omega_2 t)$$

This can be written as

$$y(t) = \frac{1}{1!} \int_{-\infty}^{+\infty} du_1 g_1(u_1) [e^{j\omega_1(t-u_1)} + e^{j\omega_2(t-u_1)}] \\ + \frac{1}{2!} \int_{-\infty}^{+\infty} du_1 \int_{-\infty}^{+\infty} du_2 g_2(u_1, u_2) [e^{j\omega_1(t-u_1)} + e^{j\omega_2(t-u_1)}] [e^{j\omega_1(t-u_2)} + e^{j\omega_2(t-u_2)}]$$

Volterra Series

Define

$$T_1 = e^{j\omega_1 t}, \quad T_2 = e^{j\omega_2 t}$$

$$U_{11} = e^{-j\omega_1 u_1} \quad U_{12} = e^{-j\omega_1 u_2}$$

$$U_{22} = e^{-j\omega_2 u_2} \quad U_{21} = e^{-j\omega_2 u_1}$$

This gives

$$\begin{aligned} y(t) = & T_1 \int_{-\infty}^{+\infty} du_1 g_1(u_1) U_{11} + T_2 \int_{-\infty}^{+\infty} du_1 g_1(u_1) U_{21} \\ & + \frac{1}{2!} \int_{-\infty}^{+\infty} du_1 \int_{-\infty}^{+\infty} du_2 g_2(u_1, u_2) [T_1 U_{11} + T_2 U_{21}] [T_1 U_{12} + T_2 U_{22}] \end{aligned}$$

or

$$y(t) = I_1 + I_2 + I_3 + I_4 + I_5 + I_6$$

Volterra Series

in which

$$I_1 = T_1 \int_{-\infty}^{+\infty} du_1 g_1(u_1) U_{11} \rightarrow I_1 = T_1 G_1(f_1)$$

$$I_2 = T_2 \int_{-\infty}^{+\infty} du_1 g_1(u_1) U_{21} \rightarrow I_2 = T_2 G_1(f_2)$$

$G_1(f)$ is the Fourier transform of $g_1(u)$ evaluated at f

Volterra Series

$$I_3 = T_1^2 \frac{1}{2!} \int_{-\infty}^{+\infty} du_1 \int_{-\infty}^{+\infty} du_2 g_2(u_1, u_2) U_{11} U_{12} = \frac{1}{2} T_1^2 G_2(f_1, f_1)$$

$$I_4 = \frac{1}{2!} T_1 T_2 \int_{-\infty}^{+\infty} du_1 \int_{-\infty}^{+\infty} du_2 g_2(u_1, u_2) U_{11} U_{22} = \frac{1}{2} T_1 T_2 G_2(f_1, f_2)$$

$$I_5 = \frac{1}{2!} T_2 T_1 \int_{-\infty}^{+\infty} du_1 \int_{-\infty}^{+\infty} du_2 g_2(u_1, u_2) U_{21} U_{12} = \frac{1}{2} T_2 T_1 G_2(f_2, f_1)$$

$$I_6 = \frac{1}{2!} T_2^2 \int_{-\infty}^{+\infty} du_1 \int_{-\infty}^{+\infty} du_2 g_2(u_1, u_2) U_{21} U_{22} = \frac{1}{2} T_2^2 G_2(f_2, f_2)$$

$G_2(f_1, f_2)$ is the double Fourier transform of $g(u, v)$ evaluated at (f_1, f_2)

Volterra Series

So, $G_1(f)$ is the Fourier transform of $g_1(u)$ evaluated at f and $G_2(f_1, f_2)$ is the double Fourier transform of $g(u, v)$ evaluated at (f_1, f_2)

We can also express $y(t)$ as:

$$y(t) = y_1(t) + y_2(t)$$

in which

$$y_1(t) = T_1 G_1(f_1) + T_2 G_1(f_2)$$

and

$$y_2(t) = \frac{1}{2!} \left[T_1^2 G_2(f_1, f_1) + T_1 T_2 G_2(f_1, f_2) + T_1 T_2 G_2(f_2, f_1) + T_2^2 G_2(f_2, f_2) \right]$$

Volterra Series

If we take into account the respective amplitudes of the tone, we have

$$x(t) = A_1 \exp(j\omega_1 t) + A_2 \exp(j\omega_2 t)$$

We can make the transformation

$$T_1 \rightarrow A_1 T_1 \quad \text{and} \quad T_2 \rightarrow A_2 T_2$$

$$y(t) = \int_{-\infty}^{+\infty} du_1 g_1(u_1) \left[A_1 e^{j\omega_1(t-u_1)} + A_2 e^{j\omega_2(t-u_1)} \right]$$

$$+ \frac{1}{2!} \int_{-\infty}^{+\infty} du_1 \int_{-\infty}^{+\infty} du_2 g_2(u_1, u_2) \left[A_1 e^{j\omega_1(t-u_1)} + A_2 e^{j\omega_2(t-u_1)} \right]$$

$$\times \left[A_1 e^{j\omega_1(t-u_2)} + A_2 e^{j\omega_2(t-u_2)} \right]$$

$$y_1(t) = \underbrace{A_1 T_1 G_1(f_1)}_{A\text{-Term}=H_A} + \underbrace{A_2 T_2 G_1(f_2)}_{B\text{-Term}=H_B}$$

Volterra Series

$$y_2(t) = \frac{1}{2!} \left[\underbrace{A_1^2 T_1^2 G_2(f_1, f_1)}_{C\text{-Term}=H_C} + \underbrace{A_1 T_1 A_2 T_2 G_2(f_1, f_2) + A_1 T_1 A_2 T_2 G_2(f_2, f_1)}_{D\text{-Term}=H_D} + \underbrace{A_2^2 T_2^2 G_2(f_2, f_2)}_{E\text{-Term}=H_E} \right]$$

If we choose $f_2 = kf_1$, then $T_1 \rightarrow f_1$ and $T_2 \rightarrow kf_1$.

In general, $\omega_2 = k\omega_1$ so that if

$$T_1 \rightarrow f_1, \quad T_2 \rightarrow kf_1$$

$H_A = A\text{-Term}$ contains terms in f_1
 $H_B = B\text{-Term}$ contains terms in kf_1
 $H_C = C\text{-Term}$ contains terms in $2f_1$
 $H_D = D\text{-Term}$ contains terms in $2kf_1$
 $H_E = E\text{-Term}$ contains terms in $(k+1)f_1$

Volterra Series

- First determine the X parameters of the system
- Next, provide excitation $a(t)$

$$a(t) = A_1 \exp(j\omega_1 t) + A_2 \exp(j\omega_2 t)$$

- Next, calculate b in phasor domain using X parameters

$$\mathbf{b} = \mathbf{X}\mathbf{a}$$

- For each port, the scattered wave will include contributions from all harmonics

$$b_p = H_A + H_B + H_C + H_D + H_E$$

Volterra Series

Finally, a relationship can be obtained to extract Volterra kernel Fourier transforms

$$\text{A-Term:} \rightarrow G_1(f_1) = \frac{H_A}{A_1} \qquad \text{B-Term:} \rightarrow G_1(f_2) = \frac{H_B}{A_2}$$

$$\text{C-Term:} \rightarrow G_2(f_1, f_1) = \frac{2H_C}{A_1^2}$$

$$\text{D-Term:} \rightarrow G_2(f_2, f_2) = \frac{2H_D}{A_2^2}$$

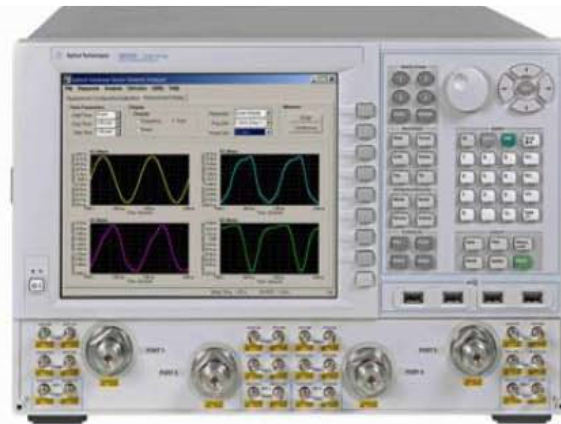
$$\text{E-Term:} \rightarrow G_2(f_1, f_2) = \frac{H_E}{A_1 A_2}$$

Volterra Series

TABLE OF VOLTERRA KERNEL TRANSFORMS

| Term | Wave | Coefficient | Constant | index | k=1 | k = 2 | k = 3 | k = 3 |
|--------|-----------|-----------------|------------|-------------|---------|---------|---------|---------|
| A-Term | T_1 | $G_1(f_1)$ | A_1 | f_1 | f_1 | f_1 | f_1 | f_1 |
| B-Term | T_2 | $G_1(f_2)$ | A_2 | $k f_1$ | f_1 | $2 f_1$ | $3 f_1$ | $4 f_1$ |
| C-Term | T_1^2 | $G_2(f_1, f_1)$ | $A_1^2/2!$ | $2 f_1$ | $2 f_1$ | $2 f_1$ | $2 f_1$ | $2 f_1$ |
| D-Term | T_2^2 | $G_2(f_2, f_2)$ | $A_2^2/2!$ | $2k f_1$ | $2 f_1$ | $4 f_1$ | $6 f_1$ | $8 f_1$ |
| E-Term | $T_1 T_2$ | $G_2(f_1, f_2)$ | $A_1 A_2$ | $(k+1) f_1$ | $2 f_1$ | $3 f_1$ | $4 f_1$ | $5 f_1$ |

Nonlinear Vector Network Analyzer (NVNA)



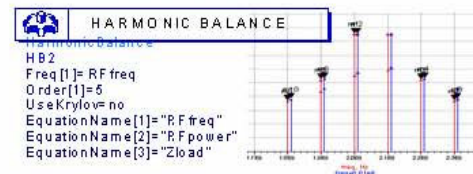
NVNA:
Measure device X-parameters



ADS:
Simulate using X-parameters

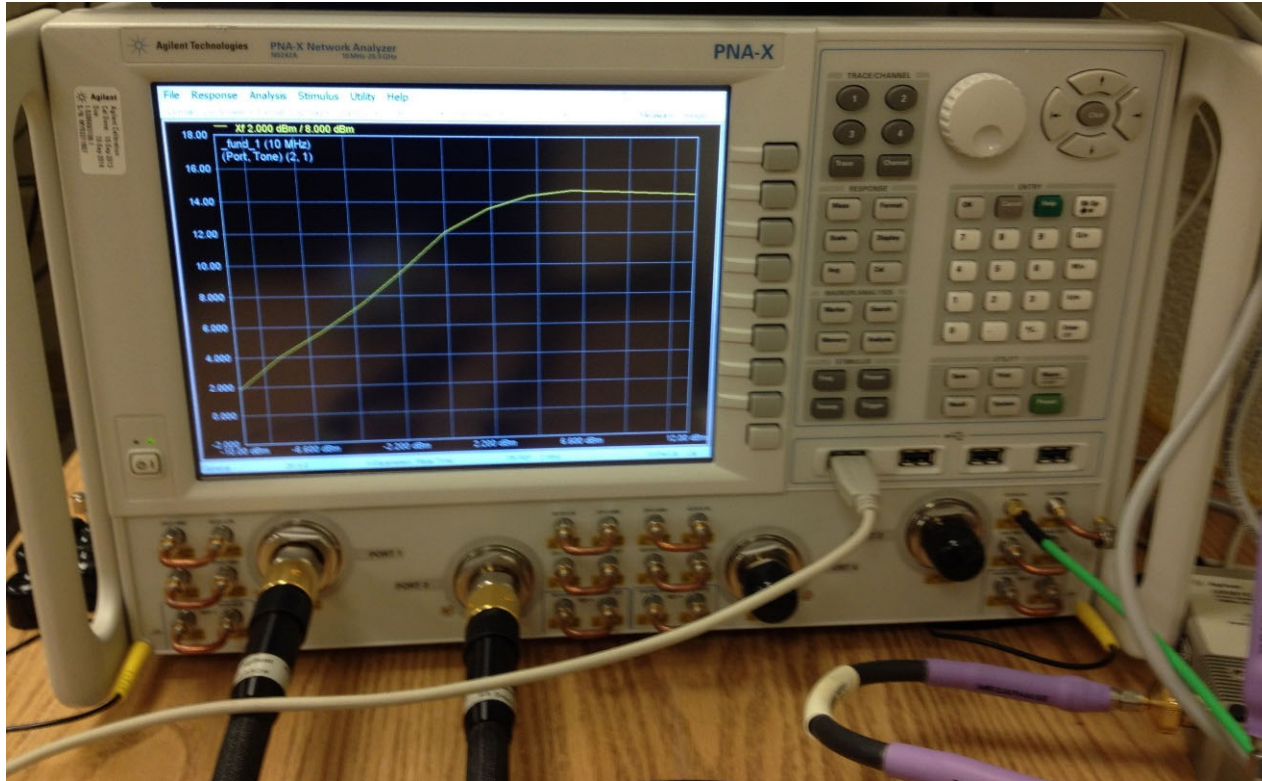


ADS:
Design using X-parameters



NVNA instruments will gradually replace all VNAs

Nonlinear Vector Network Analyzer (NVNA)*



*L. Betts, "X-Parameters and NVNA...", May 9, 2009.